

采用微型晶圆级芯片封装的 TPS63036 高效率降压/升压转换器

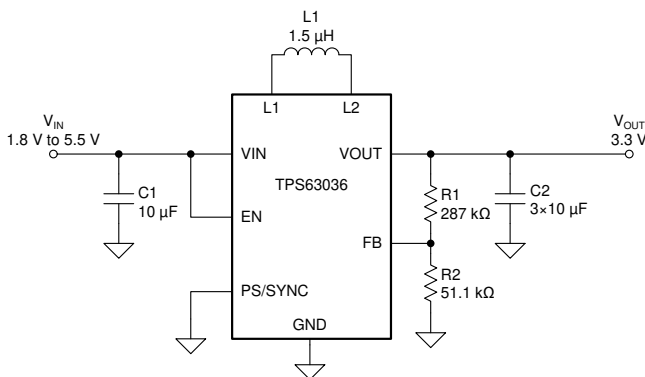
1 特性

- 输入电压范围：1.8V 至 5.5V
(器件启动时大于 2V)
- 可调节输出电压范围：1.2V 至 5.5V
- 在整个负载范围内具有高效率
 - 静态工作电流：25 μ A
 - 可无缝转换至省电模式
- 平均电流模式降压/升压架构
 - 模式间自动转换
 - 2.4MHz 固定频率工作
 - 可与外部时钟同步
- 安全、可靠运行 具有
 - 过热和过压保护
 - 关断期间负载断开
- 微型 8 引脚晶圆级芯片封装 (WCSP): 1.814mm $\times$ 1.076mm

2 应用

- 电池电压调节 (耳机和耳塞、摄像头、增强现实眼镜、电子玩具和机器人玩具、个人医疗产品)
- Wi-Fi®或 蓝牙®模块电源 (IP 网络摄像头、无线接入点、单板计算机、便携式 POS、无线传感器)
- LED/激光电源 (条形码扫描仪、激光测距仪)

T48 路多路复用 LC6948



3 说明

TPS63036 是一款同相降压-升压转换器，能够对输入电源实施升压或降压操作并最终提供稳定的输出电压。此升压/降压转换器基于一个频率固定的脉宽调制 (PWM) 控制器。该控制器可通过同步整流实现效率最大化。在负载电流较低的情况下，该转换器会进入节能模式，以在宽负载电流范围内保持高效率。禁用省电模式则会强制转换器以固定开关频率运行。

开关内的最大平均电流被限制在 1000mA (典型值)。可使用一个外部电阻分压器对输出电压进行编程。

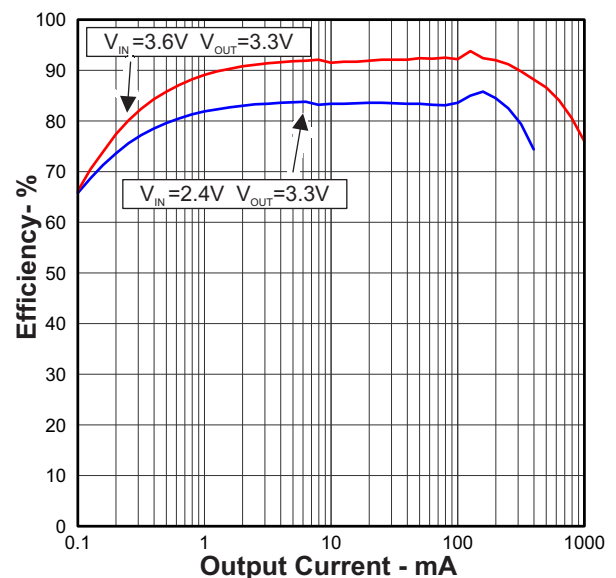
可通过禁用转换器来最大限度地减少电池消耗。在关断期间，负载与电源断开。

器件信息⁽¹⁾

器件型号	封装	封装尺寸 (标称值)
TPS63036	WCSP (8)	1.814mm $\times$ 1.076mm

(1) 如需了解所有可用封装，请参阅产品说明书末尾的可订购产品附录。

效率与输出电流间的关系



目录

1	特性	1	7.4	Device Functional Modes.....	7
2	应用	1	8	Application and Implementation	10
3	说明	1	8.1	Application Information.....	10
4	修订历史记录	2	8.2	Typical Application	10
5	Pin Configuration and Functions	3	9	Power Supply Recommendations	17
6	Specifications.....	3	10	Layout.....	17
6.1	Absolute Maximum Ratings	3	10.1	Layout Guidelines	17
6.2	ESD Ratings.....	3	10.2	Layout Example	17
6.3	Recommended Operating Conditions.....	3	10.3	Thermal Considerations	17
6.4	Thermal Information	4	11	器件和文档支持	18
6.5	Electrical Characteristics.....	4	11.1	器件支持	18
6.6	Typical Characteristics	5	11.2	社区资源	18
7	Detailed Description	6	11.3	商标	18
7.1	Overview	6	11.4	静电放电警告	18
7.2	Functional Block Diagram	6	11.5	Glossary	18
7.3	Feature Description.....	6	12	机械、封装和可订购信息	18

4 修订历史记录

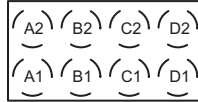
注：之前版本的页码可能与当前版本有所不同。

Changes from Revision A (August 2015) to Revision B	Page
• 更新了 特性 和 应用	1
• 更正了 特性 和 器件信息 表中的封装尺寸	1
• 更正了效率图	1
• Removed hints to fixed output voltage versions (for example, in the <i>Pin Functions</i> table).....	3

Changes from Original (August 2012) to Revision A	Page
• 已添加 添加了 <i>ESD</i> 额定值 表、特性 说明 部分、器件功能模式、应用和实施 部分、电源相关建议 部分、布局 部分、器件和文档支持 部分以及机械、封装和可订购信息 部分	1
• Removed <i>Available Output Voltage Options</i> table	3
• Removed <i>Packaging Information</i> section	17

5 Pin Configuration and Functions

**YFG Package
8-Pin WCSP
Top View**



Pin Functions

PIN		TYPE	DESCRIPTION
NAME	NO.		
EN	A2	Input	Enable input (1 enabled, 0 disabled)
FB	D2	Input	Voltage feedback pin
GND	C2	—	Control/logic ground
PS/SYNC	B2	Input	Enable/disable power-save mode (1 disabled, 0 enabled, clock signal for synchronization)
L1	B1	Input	Connection for inductor
L2	C1	Input	Connection for inductor
VIN	A1	Input	Supply voltage for power stage
VOUT	D1	Output	Buck-boost converter output

6 Specifications

6.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted)⁽¹⁾

	MIN	MAX	UNIT
Input voltage on VIN, L1, L2, VOUT, PS/SYNC, EN, FB	−0.3	7	V
Operating virtual junction temperature, T _J	−40	150	°C
Storage temperature, T _{stg}	−65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

		VALUE	UNIT
V _(ESD) Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±2000	V
	Charged-device model (CDM), per JEDEC specification JESD22-C101 ⁽²⁾	±1000	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

	MIN	MAX	UNIT
Supply voltage at VIN	1.8	5.5	V
Operating free air temperature, T _A	−40	85	°C
Operating virtual junction temperature, T _J	−40	125	°C

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TPS63036	UNIT
		YFG (WCSP)	
		8 PINS	
R _{θJA}	Junction-to-ambient thermal resistance	84	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	0.7	°C/W
R _{θJB}	Junction-to-board thermal resistance	43.9	°C/W
ψ _{JT}	Junction-to-top characterization parameter	2.9	°C/W
ψ _{JB}	Junction-to-board characterization parameter	43.7	°C/W
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	—	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953](#).

6.5 Electrical Characteristics

Over recommended free-air temperature range and over recommended input voltage range (typical at an ambient temperature range of 25°C) unless otherwise noted.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{IN}	Input voltage range		1.8 ⁽¹⁾		5.5	V
V _{OUT}	Output voltage range		1.2		5.5	V
	Duty cycle in step-down conversion		20%			
V _{FB}	Feedback voltage	PS/SYNC = V _{IN} I _{OUT} < 5 mA	495	500	505	mV
V _{FB}	Feedback voltage	PS/SYNC = GND referenced to 500 mV I _{OUT} < 5 mA	-3%		+6%	
	Load regulation	PS/SYNC = GND		0.008		%/mA
f	Oscillator frequency		1800	2000	2200	kHz
	Frequency range for synchronization		2200	2400	2600	kHz
I _{SW}	Average input current limit	V _{IN} = 3.6 V, T _A = 25°C ⁽²⁾		1000		mA
	High-side switch ON-resistance	V _{IN} = 3.6 V		200		mΩ
	Low-side switch ON-resistance	V _{IN} = 3.6 V		200		mΩ
	Line regulation			0.5%		
I _q	Quiescent current	V _{IN}		25	35	μA
		V _{OUT}		4	6	μA
I _S	Shutdown current	V _{EN} = 0 V, V _{IN} = 3.6 V		0.1	0.9	μA
CONTROL STAGE						
V _{UVLO}	Undervoltage lockout threshold falling		1.4	1.5	1.6	V
	Undervoltage lockout threshold raising		1.6	1.8	2.0	V
V _{IL}	EN, PS/SYNC input low voltage				0.4	V
V _{IH}	EN, PS/SYNC input high voltage		1.2			V
	EN, PS/SYNC input current	Clamped on GND or V _{IN}		0.01	0.1	μA
	Overtemperature protection			140		°C
	Overtemperature hysteresis			20		°C

(1) The typical required supply voltage for start-up is 2 V. The part is functional down to 1.8 V.

(2) For the minimum specified average input current limit at V_{OUT} = 2.5 V, 3.3 V and 4.5 V refer to curve in [Figure 1](#). For the maximum specified average input current limit at V_{OUT} = 2.5 V, 3.3 V and 4.5 V refer to curve in [Figure 2](#).

6.6 Typical Characteristics

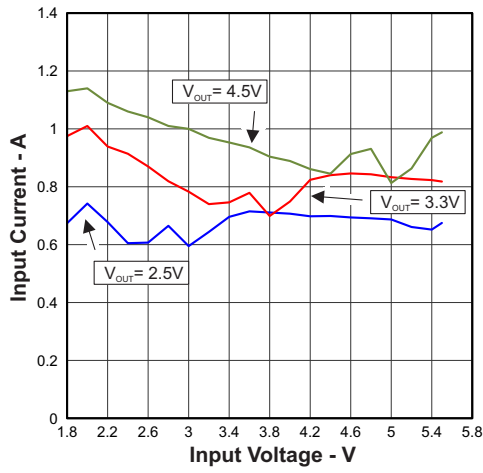


Figure 1. Minimum Input Current vs Input Voltage

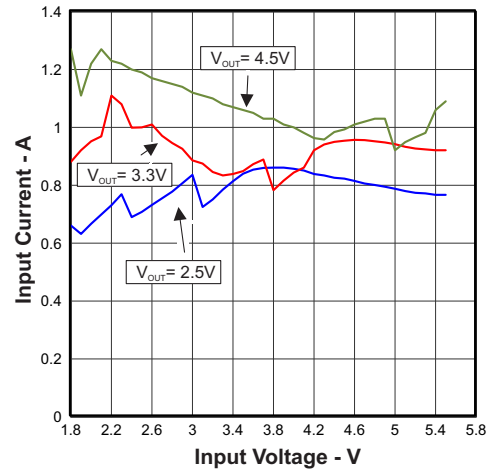


Figure 2. Maximum Input Current vs Input Voltage

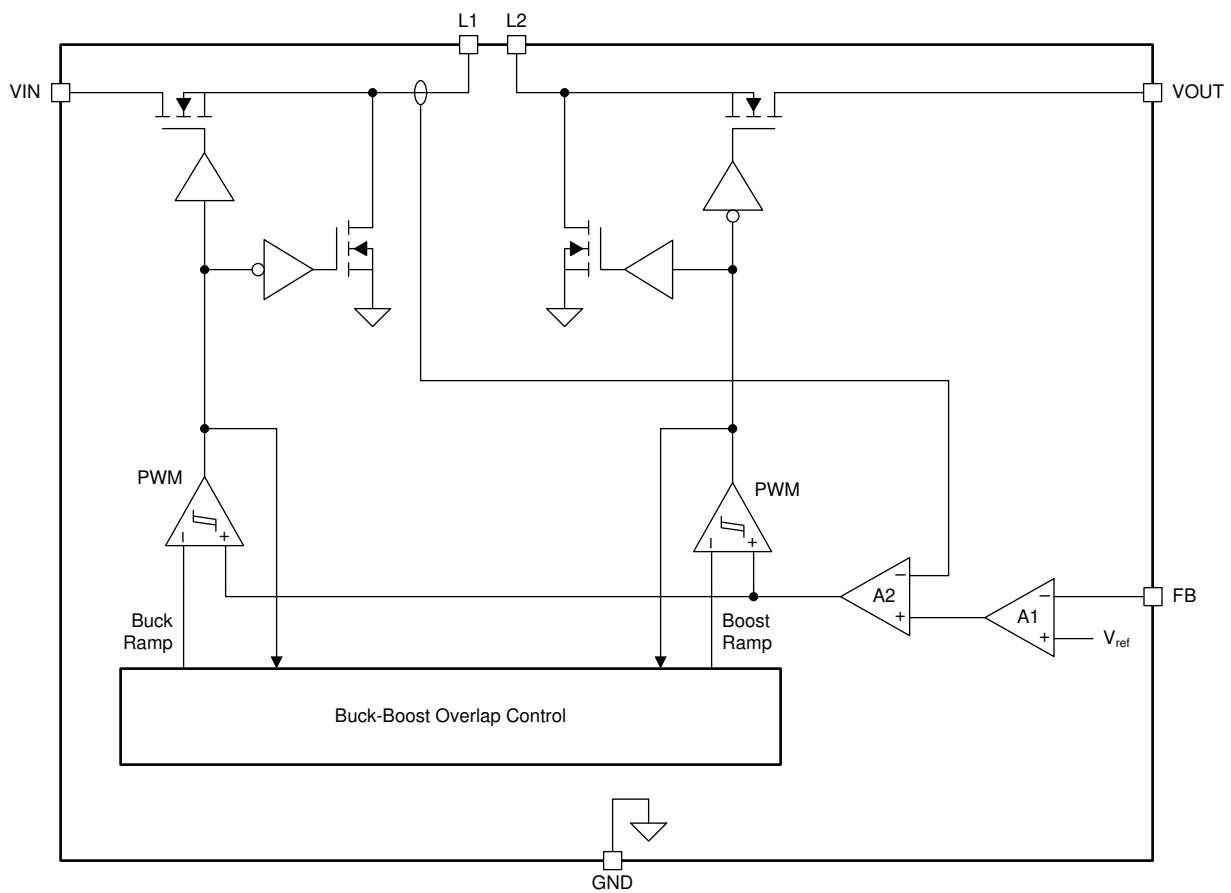
7 Detailed Description

7.1 Overview

The controller circuit of the device is based on an average current mode topology. The controller also uses input and output voltage feedforward. Changes of input and output voltage are monitored and immediately can change the duty cycle in the modulator to achieve a fast response to those errors. The voltage error amplifier gets its feedback input from the FB pin. A resistive voltage divider must be connected to that pin. The feedback voltage will be compared with the internal reference voltage to generate a stable and accurate output voltage.

The device uses 4 internal N-channel MOSFETs to maintain synchronous power conversion at all possible operating conditions. This enables the device to keep high efficiency over a wide input voltage and output power range. Due to the 4-switch topology, the load is always disconnected from the input during shutdown of the converter. To protect the device from overheating an internal temperature sensor is implemented.

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 Device Enable

The device is put into operation when EN is set high. It is put into a shutdown mode when EN is set to GND. In shutdown mode, the regulator stops switching, all internal control circuitry is switched off, and the load is disconnected from the input. This means that the output voltage can drop below the input voltage during shutdown. During start-up of the converter, the duty cycle and the peak current are limited in order to avoid high peak currents flowing from the input.

Feature Description (continued)

7.3.2 Overvoltage Protection

If, for any reason, the output voltage is not fed back properly to the input of the voltage amplifier, control of the output voltage will not work anymore. Therefore overvoltage protection is implemented to avoid the output voltage exceeding critical values for the device and possibly for the system it is supplying. The implemented overvoltage protection circuit monitors the output voltage internally as well. In case it reaches the overvoltage threshold the voltage amplifier regulates the output voltage to this value.

7.3.3 Undervoltage Lockout

An undervoltage lockout function prevents device start-up if the supply voltage at VIN is lower than approximately its threshold (see [Electrical Characteristics](#) table). When in operation, the device automatically enters the shutdown mode if the voltage at VIN drops below the undervoltage lockout threshold. The device automatically restarts if the input voltage recovers to the minimum operating input voltage.

7.3.4 Overtemperature Protection

The device has a built-in temperature sensor which monitors the internal IC temperature. If the temperature exceeds the programmed threshold (see [Electrical Characteristics](#) table) the device stops operating. As soon as the IC temperature has decreased below the programmed threshold, it starts operating again. There is a built-in hysteresis to avoid unstable operation at IC temperatures at the overtemperature threshold.

7.4 Device Functional Modes

7.4.1 Soft-Start and Short Circuit Protection

After being enabled, the device starts operating. The average input current limit ramps up from an initial 400 mA following the output voltage increasing. At an output voltage of about 1.2 V, the current limit is at its nominal value. If the output voltage does not increase, the current limit will also not increase. The device ramps up the output voltage in a controlled manner even if a large capacitor is connected at the output. When the output voltage does not increase above 1.2 V, the device assumes a short circuit at the output, and keeps the current limit low to protect itself and the application. At a short on the output during operation, the current limit also is decreased accordingly.

7.4.2 Buck-Boost Operation

To regulate the output voltage at all possible input voltage conditions, the device automatically switches from step-down operation to boost operation and back as required by the configuration. It always uses one active switch, one rectifying switch, one switch permanently on, and one switch permanently off. Therefore, it operates as a step-down converter (buck) when the input voltage is higher than the output voltage, and as a boost converter when the input voltage is lower than the output voltage. There is no mode of operation in which all 4 switches are permanently switching. Controlling the switches this way allows the converter to maintain high efficiency at the most important point of operation, when input voltage is close to the output voltage. The RMS current through the switches and the inductor is kept at a minimum, to minimize switching and conduction losses. For the remaining 2 switches, one is kept permanently on and the other is kept permanently off, thus causing no switching losses.

7.4.3 Control Loop

The average inductor current is regulated by a fast current regulator loop which is controlled by a voltage control loop. [Figure 3](#) shows the control loop.

The noninverting input of the trans-conductance amplifier Gmv can be assumed to be constant. The output of Gmv defines the average inductor current. The inductor current is reconstructed measuring the current through the high-side buck MOSFET. This current corresponds exactly to the inductor current in boost mode. In buck mode the current is measured during the ON-time of the same MOSFET. During the OFF-time the current is reconstructed internally starting from the peak value reached at the end of the ON-time cycle. The average current is then compared to the desired value and the difference, or current error, is amplified and compared to the sawtooth ramp of either the buck or the boost.

Device Functional Modes (continued)

The Buck-Boost Overlap Control makes sure that the classical buck-boost function, which would cause two switches to be on every half a cycle, is avoided. Thanks to this block whenever all switches becomes active during one clock cycle, the two ramps are shifted away from each other, on the other hand when there is no switching activities because there is a gap between the ramps, the ramps are moved closer together. As a result the number of classical buck-boost cycles or no switching is reduced to a minimum and high-efficiency values have been achieved.

Slope compensation is not required to avoid subharmonic oscillation which are otherwise observed when working with peak current mode control with $D > 0.5$.

Nevertheless the amplified inductor current downslope at one input of the PWM comparator must not exceed the oscillator ramp slope at the other comparator input. This purpose is reached limiting the gain of the current amplifier.

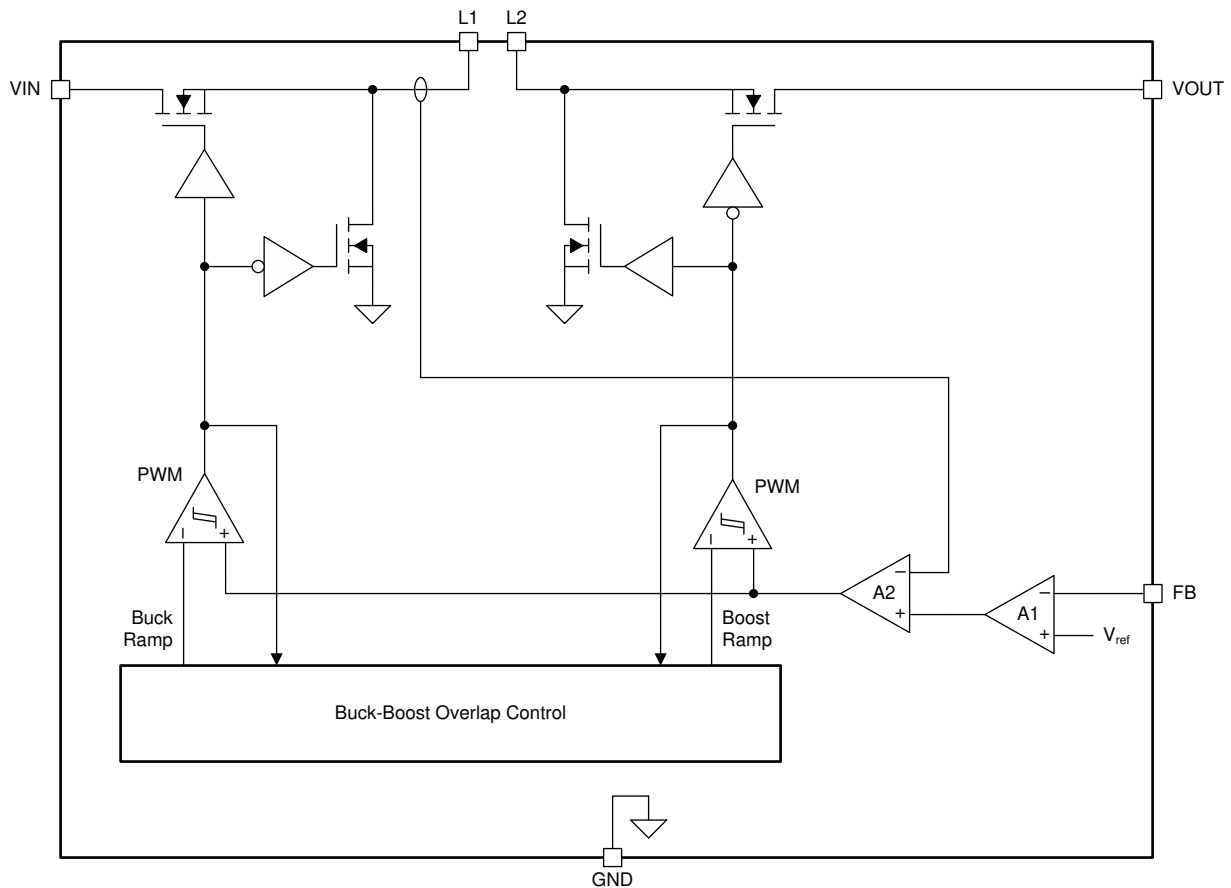


Figure 3. Average Current Mode Control

7.4.4 Power-Save Mode and Synchronization

The PS/SYNC pin can be used to select different operation modes. Power-save mode is used to improve efficiency at light load. To enable power-save mode, PS/SYNC must be set low. If PS/SYNC is set low then power-save mode is entered when the average inductor current gets lower than about 100 mA. At this point the converter operates with reduced switching frequency and with a minimum quiescent current to maintain high efficiency.

Device Functional Modes (continued)

During the power-save mode, the output voltage is monitored with a comparator by the threshold comp low and comp high. When the device enters power-save mode, the converter stops operating and the output voltage drops. The slope of the output voltage depends on the load and the value of output capacitance. As the output voltage falls below the comp low threshold, the device ramps up the output voltage again, by starting operation using a programmed average inductor current higher than required by the current load condition. Operation can last one or several pulses. The converter continues these pulses until the comp high threshold is reached and the average inductance current gets lower than about 100 mA. When the load increases above the minimum forced inductor current of about 100 mA, the device will automatically switch to PWM mode.

The power-save mode can be disabled by programming high at the PS/SYNC. Connecting a clock signal at PS/SYNC forces the device to synchronize to the connected clock frequency.

Synchronization is done by a phase-locked loop (PLL), so synchronizing to lower and higher frequencies compared to the internal clock works without any issues. The PLL can also tolerate missing clock pulses without the converter malfunctioning. The PS/SYNC input supports standard logic thresholds.

8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The TPS63036 device is a noninverting buck-boost converter that is suitable for applications that need a regulated output voltage from an input supply that can be higher or lower than the output voltage. The device supports regulated output voltages from 1.2 V to 5.5 V.

8.2 Typical Application

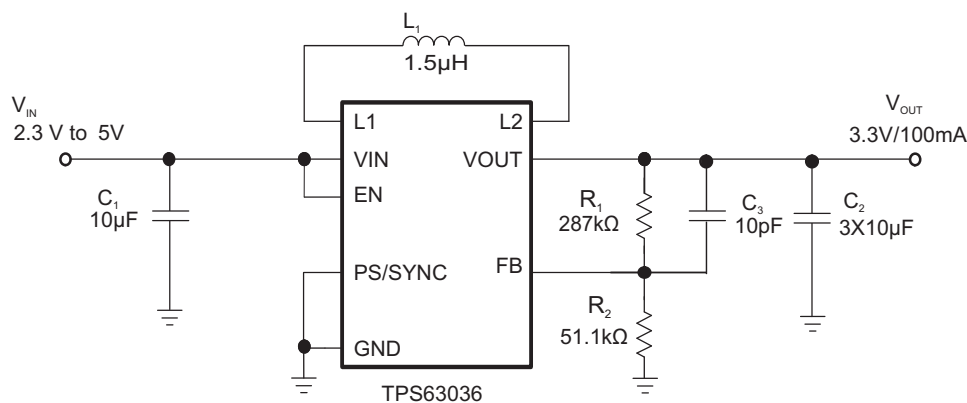


Figure 4. Typical Operating Circuit

8.2.1 Design Requirements

The design guidelines provide a component selection to operate the adjustable device within the [Recommended Operating Conditions](#).

8.2.2 Detailed Design Procedure

The design guideline provides a component selection to operate the device within the recommended operating conditions.

[Table 1](#) shows the list of components for the [Application Curves](#).

Table 1. List of Components

REFERENCE	DESCRIPTION	MANUFACTURER
	TPS63036	Texas Instruments
L1	1.5 μH, 3 mm x 3 mm x 1.5 mm	Coilcraft, LPS3015-152MLC
C1	10 μF 6.3V, 0603, X7R ceramic	GRM188R60J106KME8 4D, Murata
C2	3 × 10 μF 6.3V, 0603, X7R ceramic	GRM188R60J106KME8 4D, Murata
R1, R2	Depending on the output voltage at TPS63036	

The TPS63036 buck-boost converter has internal loop compensation. Therefore, the external L-C filter has to be selected to work with the internal compensation. As a general rule of thumb, the product $L \times C$ should not move over a wide range when selecting a different output filter. However, when selecting the output filter a low limit for the inductor value exists to avoid sub-harmonic oscillation which could be caused by a far too fast ramp up of the amplified inductor current. For the TPS63036 the minimum inductor value should be kept at 1 μH . To simplify this process [Table 1](#) outlines possible inductor and capacitor value combinations.

Table 2. Output Filter Selection (Average Inductance Current up to 1 A)

INDUCTOR VALUE [μH] ⁽¹⁾	OUTPUT CAPACITOR VALUE [μF] ⁽²⁾		
	30	44	66
1.0	√	√	√
1.5	√ ⁽³⁾	√	√
2.2			√

- (1) Inductor tolerance and current de-rating is anticipated. The effective inductance can vary by 20% and –30%.
- (2) Capacitance tolerance and bias voltage de-rating is anticipated. The effective capacitance can vary by 20% and –50%.
- (3) Typical application. Other check mark indicates recommended filter combinations

8.2.2.1 Inductor Selection

For high efficiencies, the inductor should have a low DC resistance to minimize conduction losses. Especially at high-switching frequencies the core material has a higher impact on efficiency. When using small chip inductors, the efficiency is reduced mainly due to higher inductor core losses. This needs to be considered when selecting the appropriate inductor. The inductor value determines the inductor ripple current. The larger the inductor value, the smaller the inductor ripple current and the lower the conduction losses of the converter. Conversely, larger inductor values cause a slower load transient response. To avoid saturation of the inductor, with the chosen inductance value, the peak current for the inductor in steady-state operation can be calculated. Only the equation which defines the switch current in boost mode is reported because this is providing the highest value of current and represents the critical current value for selecting the right inductor.

$$\text{Duty Cycle Boost} \quad D = \frac{V_{\text{out}} - V_{\text{in}}}{V_{\text{out}}} \quad (1)$$

$$I_{\text{PEAK}} = I_{\text{SW_MAX}} + \frac{V_{\text{in}} \times D}{2 \times f \times L}$$

where

- D = Duty cycle in boost mode
- f = Converter switching frequency (typical 2 MHz)
- L = Selected inductor value
- η = Estimated converter efficiency (use the number from the efficiency curves or 0.80 as an assumption)
- $I_{\text{SW_MAX}}$ = Maximum average input current ([Figure 6](#))

NOTE

The calculation must be done for the minimum input voltage which is possible to have in boost mode.

Consider the load transients and error conditions that can cause higher inductor currents. Consider when selecting an appropriate inductor. Please refer to [Table 3](#) for typical inductors.

The size of the inductor can also affect the stability of the feedback loop. In particular the boost transfer function exhibits a right half-plane zero, whose frequency is inverse proportional to the inductor value and the load current. This means as higher the value of inductance and load current is the more possibilities has the right plane zero to be moved at lower frequency. This could degrade the phase margin of the feedback loop. TI recommends to choose the value of the inductor in order to have the frequency of the right half plane zero >400 kHz. The frequency of the RHPZ can be calculated using equation [Equation 2](#).

$$f_{\text{RHPZ}} = \frac{(1 - D)^2 \times V_{\text{out}}}{2\pi \times I_{\text{out}} \times L}$$

where

- D = Duty cycle in boost mode

(3)

NOTE

The calculation must be done for the minimum input voltage which is possible to have in boost mode.

Table 3. Inductor Selection

INDUCTOR VALUE	COMPONENT SUPPLIER	SIZE (LxWxH mm)	I _{sat} /DCR
1 μH	TOKO 1286AS-H-1R0M	2x1.6x1.2	2.3A/78mΩ
1 μH	Coilcraft XFL4020-102	4 x 4 x 2.1	5.1A/10.8 mΩ
1 μH	Coilcraft XFL3012-102	3 x 3 x 1.2	2.2 A/35 mΩ
1.5μH	TOKO, 1286AS-H-1R5M	2 x 1.6 x 1.2	4.4A/ 14.40mΩ
1.5μH	Coilcraft, LPS3015-152MLC	3 x 3 x 1.5	2.1A/100mΩ
1.5μH	TOKO, 1269AS-H-1R5M	2.5 x 2 x 1	2.1A/108mΩ
2.2μH	TOKO D1286AS-H-2R2M	2 x 1.6 x 1.2	1.6A/192mΩ

8.2.2.2 Capacitor Selection

8.2.2.2.1 Input Capacitor

At least a 10-μF input capacitor is recommended to improve transient behavior of the regulator and EMI behavior of the total power supply circuit. A ceramic capacitor placed as close as possible to the VIN and GND pins of the IC is recommended.

8.2.2.2.2 Output Capacitor

For the output capacitor, use of a small ceramic capacitors placed as close as possible to the VOUT and GND pins of the IC is recommended. If, for any reason, the application requires the use of large capacitors which can not be placed close to the IC, use a smaller ceramic capacitor in parallel to the large capacitor. The small capacitor should be placed as close as possible to the VOUT and GND pins of the IC. The recommended typical output capacitor value is 30 μF.

There is also no upper limit for the output capacitance value. Larger capacitors will cause lower output voltage ripple as well as lower output voltage drop during load transients.

When choosing input and output capacitors, it needs to be kept in mind, that the value of capacitance experiences significant losses from their rated value depending on the operating temperature and the operating DC voltage. It is not uncommon for a small surface mount ceramic capacitor to lose 50% and more of its rated capacitance. For this reason it could be important to use a larger value of capacitance or a capacitor with higher voltage rating in order to ensure the required capacitance at the full operating voltage.

8.2.2.3 Setting the Output Voltage

The output voltage of the TPS63036 is set by an external resistor divider. The resistor divider must be connected between VOUT, FB and GND. When the output voltage is regulated, the typical value of the voltage at the FB pin is 500 mV. The maximum recommended value for the output voltage is 5.5 V. The typical current into the FB pin is 0.01 μA, and the voltage across the resistor between FB and GND, R2, is typically 500 mV. Based on these two values, the recommended value for R2 should be lower than 100 kΩ, in order to set the divider current at 5 μA or higher. From that, the value of the resistor connected between VOUT and FB, R1, depending on the needed output voltage (V_{OUT}), can be calculated using [Equation 4](#):

$$R1 = R2 \times \left(\frac{V_{\text{OUT}}}{V_{\text{FB}}} - 1 \right) \quad (4)$$

A small capacitor C3 = 10 pF, in parallel with R1 needs to be placed when using the power-save mode, to improve considerably the output voltage ripple.

8.2.2.4 Current Limit

To protect the device and the application, the average input current is limited internally on the IC. At nominal operating conditions, this current limit is constant. The current limit value can be found in the [Electrical Characteristics](#) table. The current limit varies depending on the input voltage. A curve of the input current varying with the input voltage is shown in [Figure 5](#) and [Figure 6](#) respectively showing the minimum and the maximum current limit expected depending on input and output voltage.

Given the average input current in [Figure 5](#) is then possible to calculate the output current reached in boost mode using [Equation 5](#) and [Equation 6](#) and in buck mode using [Equation 7](#) and [Equation 8](#).

$$\text{Duty Cycle Boost} \quad D = \frac{V_{OUT} - V_{IN}}{V_{OUT}} \quad (5)$$

$$\text{Maximum Output Current Boost} \quad I_{OUT} = \eta \times I_{SW} \times (1 - D) \quad (6)$$

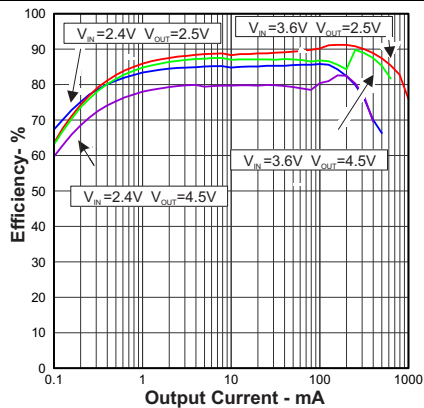
$$\text{Duty Cycle Buck} \quad D = \frac{V_{OUT}}{V_{IN}} \quad (7)$$

$$\text{Maximum Output Current Buck} \quad I_{out} = \frac{\eta \times I_{sw}}{D}$$

where

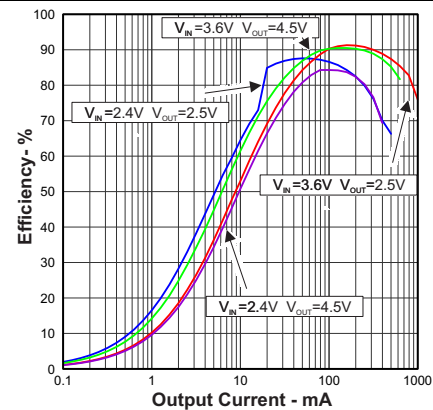
- η = Estimated converter efficiency (use the number from the efficiency curves or 0.80 as an assumption)
 - f = Converter switching frequency (typical 2 MHz)
 - L = Selected inductor value
 - I_{SW} = Minimum average input current ([Figure 5](#))
- (8)

8.2.3 Application Curves



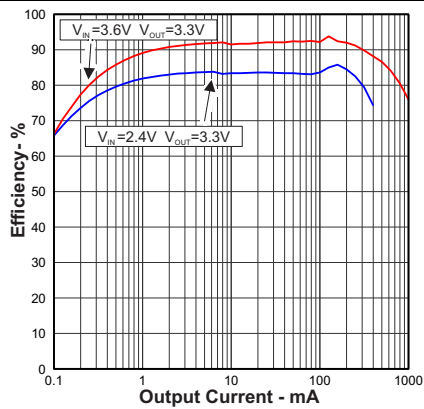
$V_{OUT} = 2.5\text{ V} / 4.5\text{ V}$

Figure 5. Efficiency vs Output Current – Power-Save Mode Enabled



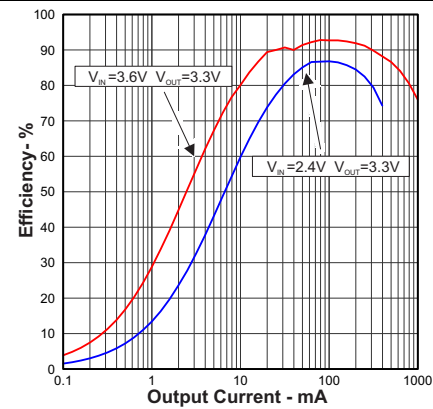
$V_{OUT} = 2.5\text{ V} / 4.5\text{ V}$

Figure 6. Efficiency vs Output Current – Power-Save Mode Disabled



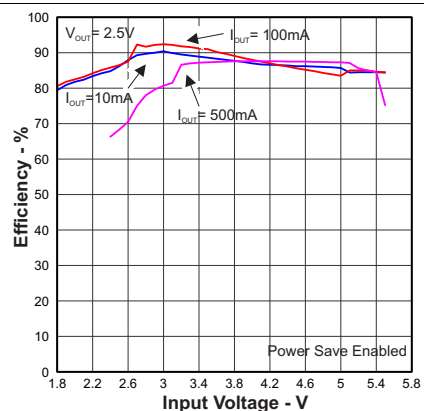
$V_{OUT} = 3.3\text{ V}$

Figure 7. Efficiency vs Output Current – Power-Save Mode Enabled



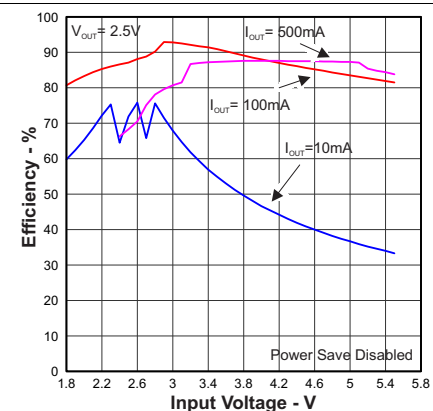
$V_{OUT} = 3.3\text{ V}$

Figure 8. Efficiency vs Output Current – Power-Save Mode Disabled



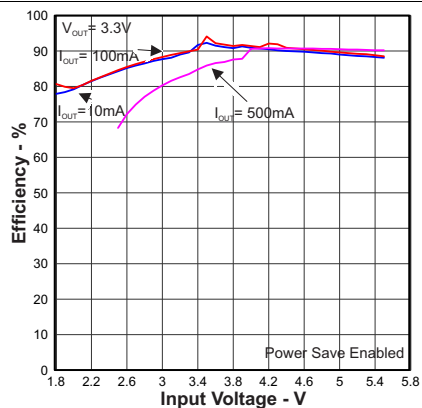
$V_{OUT} = 2.5\text{ V}, I_{OUT} = 10\text{ mA}/100\text{ mA}/500\text{ mA}$

Figure 9. Efficiency vs Input Voltage – Power-Save Mode Enabled



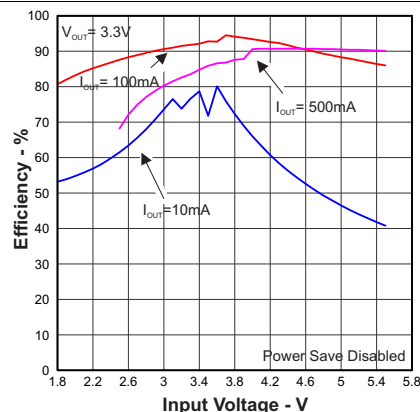
$V_{OUT} = 2.5\text{ V}, I_{OUT} = 10\text{ mA}/100\text{ mA}/500\text{ mA}$

Figure 10. Efficiency vs Input Voltage – Power-Save Mode Disabled



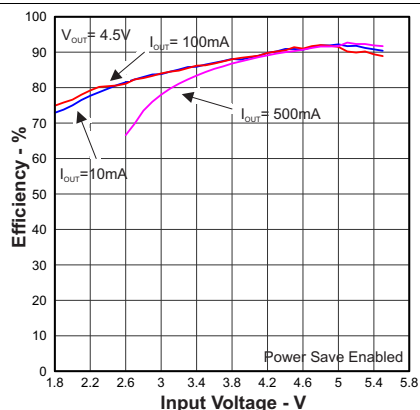
$V_{OUT} = 3.3\text{ V}$, $I_{OUT} = 10\text{ mA}/100\text{ mA}/500\text{ mA}$

Figure 11. Efficiency vs Input Voltage – Power-Save Mode Enabled



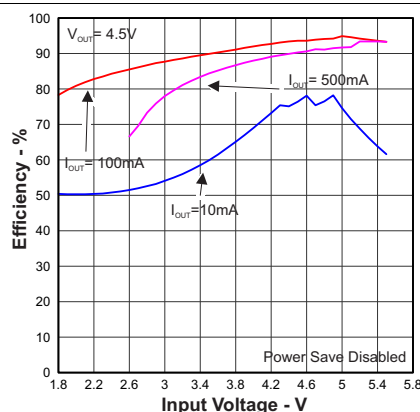
$V_{OUT} = 3.3\text{ V}$, $I_{OUT} = 10\text{ mA}/100\text{ mA}/500\text{ mA}$

Figure 12. Efficiency vs Input Voltage – Power-Save Mode Disabled



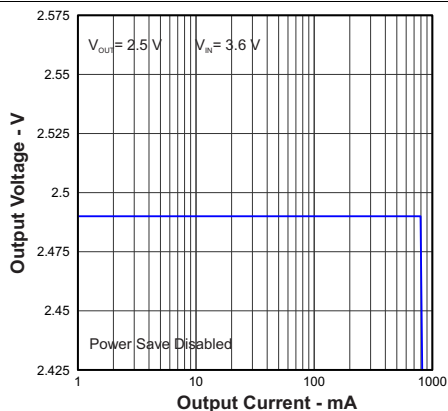
$V_{OUT} = 4.5\text{ V}$, $I_{OUT} = 10\text{ mA}/100\text{ mA}/500\text{ mA}$

Figure 13. Efficiency vs Input Voltage – Power-Save Mode Enabled



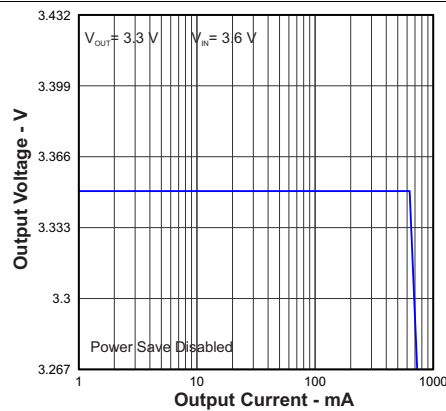
$V_{OUT} = 4.5\text{ V}$, $I_{OUT} = 10\text{ mA}/100\text{ mA}/500\text{ mA}$

Figure 14. Efficiency vs Input Voltage – Power-Save Mode Disabled



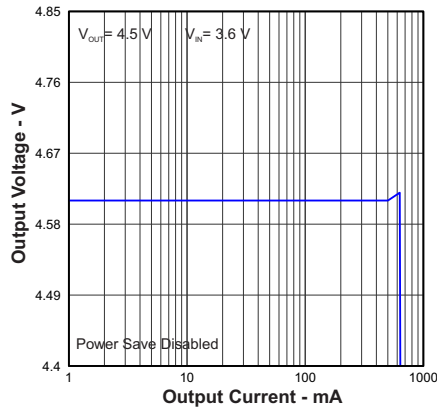
$V_{OUT} = 2.5\text{ V}$

Figure 15. Output Voltage vs Output Current



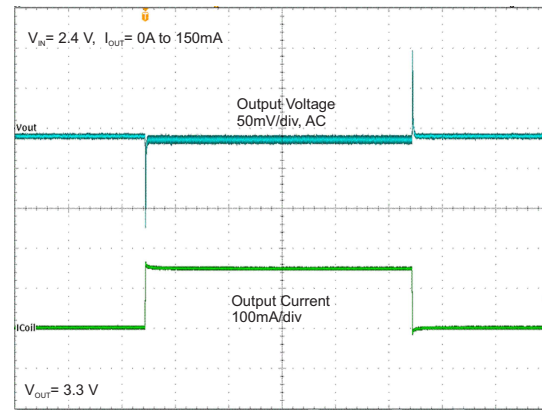
$V_{OUT} = 3.3\text{ V}$

Figure 16. Output Voltage vs Output Current



$V_{OUT} = 4.5\text{ V}$

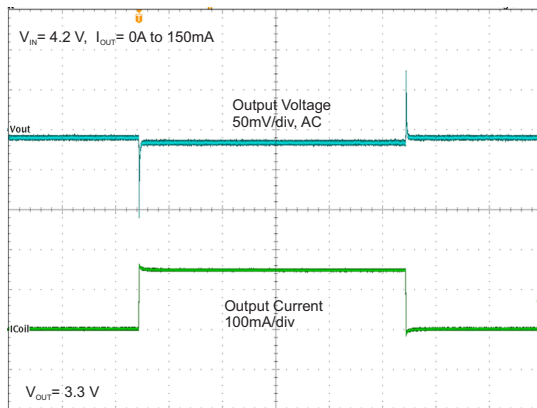
Figure 17. Output Voltage vs Output Current



Time 1ms/Div

$V_{IN} < V_{OUT}$, Load Change from 0 mA to 150 mA

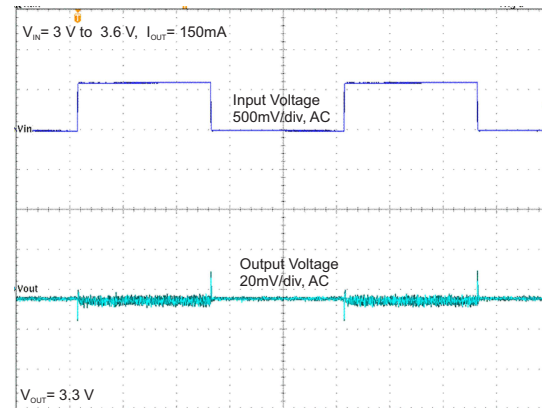
Figure 18. Load Transient Response



Time 1ms/Div

$V_{IN} > V_{OUT}$, Load Change from 0 mA to 150 mA

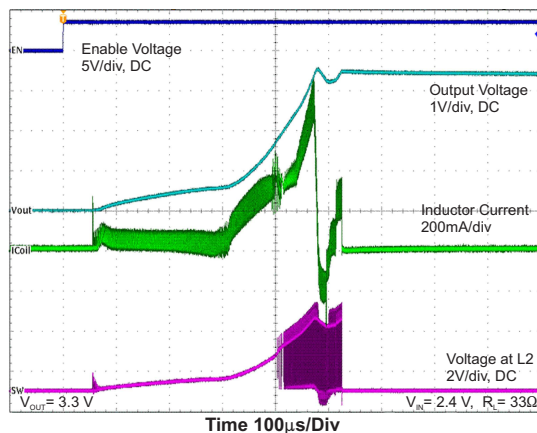
Figure 19. Load Transient Response



Time 2ms/Div

$V_{OUT} = 3.3\text{ V}$, $I_{OUT} = 150\text{ mA}$

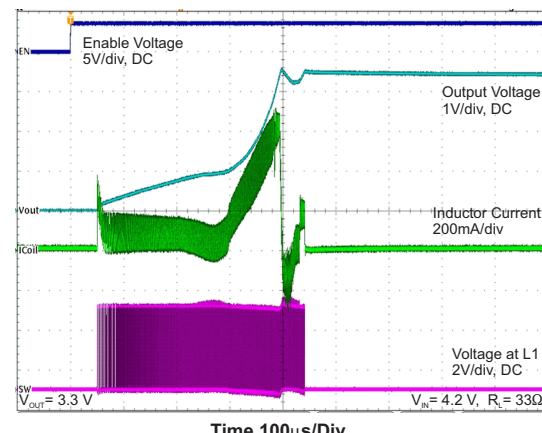
Figure 20. Line Transient Response



Time 100μs/Div

$V_{OUT} = 3.3\text{ V}$, $V_{IN} = 2.4\text{ V}$, $R_L = 33\Omega$

Figure 21. Start-Up After Enable



Time 100μs/Div

$V_{OUT} = 3.3\text{ V}$, $V_{IN} = 4.2\text{ V}$, $R_L = 33\Omega$

Figure 22. Start-Up After Enable

9 Power Supply Recommendations

The TPS63036 device has no special requirements for its input power supply. The output current of the input power supply needs to be rated according to the supply voltage, output voltage and output current of the TPS63036.

10 Layout

10.1 Layout Guidelines

For all switching power supplies, the layout is an important step in the design, especially at high peak currents and high switching frequencies. If the layout is not carefully done, the regulator could show stability problems as well as EMI problems. Therefore, use wide and short traces for the main current path and for the ground tracks. The input capacitor, output capacitor, and the inductor should be placed as close as possible to the IC.

The feedback divider should be placed as close as possible to the ground pin of the IC.

10.2 Layout Example

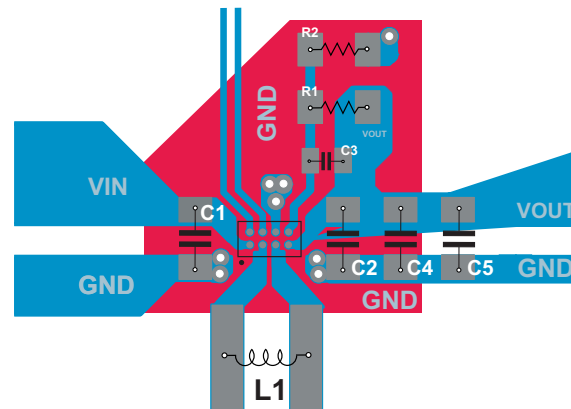


Figure 23. Layout Recommendation

10.3 Thermal Considerations

Implementation of integrated circuits in low-profile and fine-pitch surface-mount packages typically requires special attention to power dissipation. Many system-dependent issues such as thermal coupling, airflow, added heat sinks and convection surfaces, and the presence of other heat-generating components affect the power-dissipation limits of a given component.

Three basic approaches for enhancing thermal performance are listed below.

1. Improving the power dissipation capability of the PCB design
2. Improving the thermal coupling of the component to the PCB by soldering all pins to traces as wide as possible.
3. Introducing airflow in the system

The maximum recommended junction temperature (T_J) of the TPS63036 device is 125°C. The thermal resistance of this 8-pin chip-scale package (YFG) is $R_{\theta JA} = 84^\circ\text{C/W}$, if all pins are soldered. Specified regulator operation is assured to a maximum ambient temperature T_A of 85°C. Therefore, the maximum power dissipation is about 476 mW, as calculated in Equation 9. More power can be dissipated if the maximum ambient temperature of the application is lower.

$$P_{D(MAX)} = \frac{T_{J(MAX)} - T_A}{R_{\theta JA}} = \frac{125^\circ\text{C} - 85^\circ\text{C}}{84^\circ\text{C/W}} = 476 \text{ mW} \quad (9)$$

11 器件和文档支持

11.1 器件支持

11.1.1 第三方产品免责声明

TI 发布的与第三方产品或服务有关的信息，不能构成与此类产品或服务或保修的适用性有关的认可，不能构成此类产品或服务单独或与任何 TI 产品或服务一起的表示或认可。

11.2 社区资源

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

TI E2E™ Online Community *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.3 商标

E2E is a trademark of Texas Instruments.

蓝牙 is a registered trademark of Bluetooth SIG.

Wi-Fi is a registered trademark of Wi-Fi Alliance.

11.4 静电放电警告



这些装置包含有限的内置 ESD 保护。存储或装卸时，应将导线一起截短或将装置放置于导电泡棉中，以防止 MOS 门极遭受静电损伤。

11.5 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 机械、封装和可订购信息

以下页面包含机械、封装和可订购信息。这些信息是指定器件的最新可用数据。数据如有变更，恕不另行通知，且不会对此文档进行修订。如需获取此数据表的浏览器版本，请查阅左侧的导航栏。

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TPS63036YFGR	Active	Production	DSBGA (YFG) 8	3000 LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	S63036
TPS63036YFGT	Active	Production	DSBGA (YFG) 8	250 SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	S63036

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

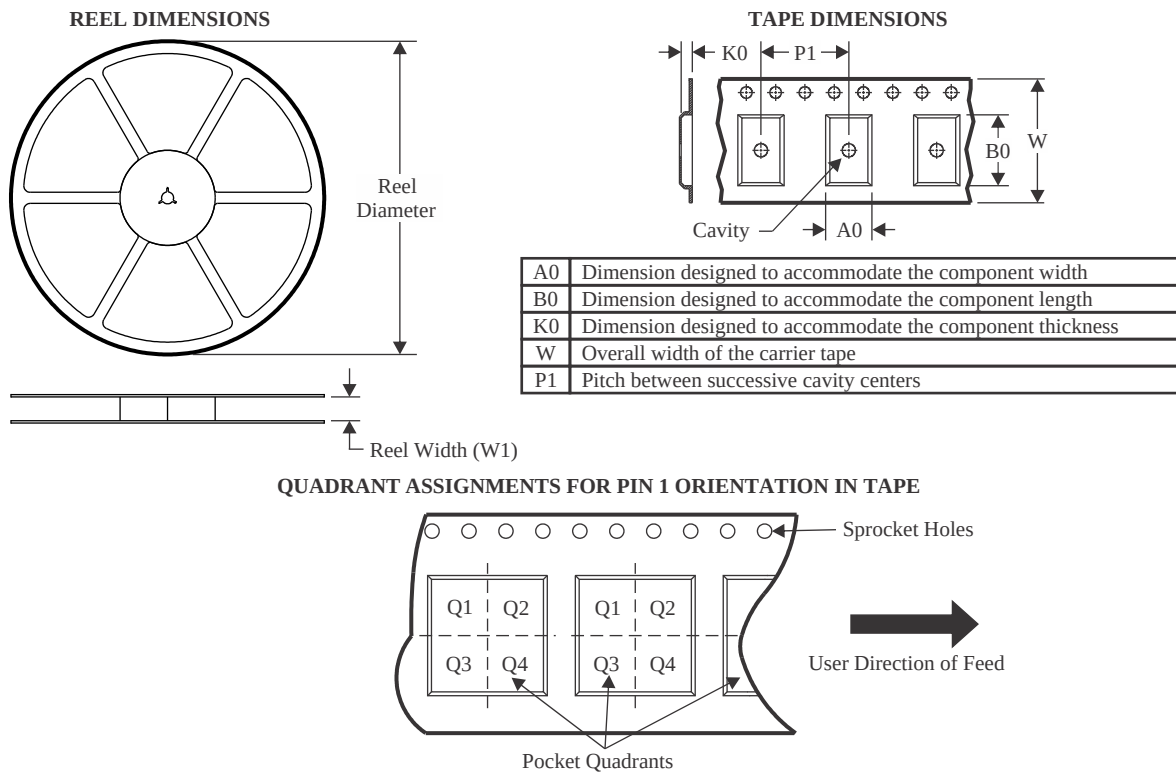
⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

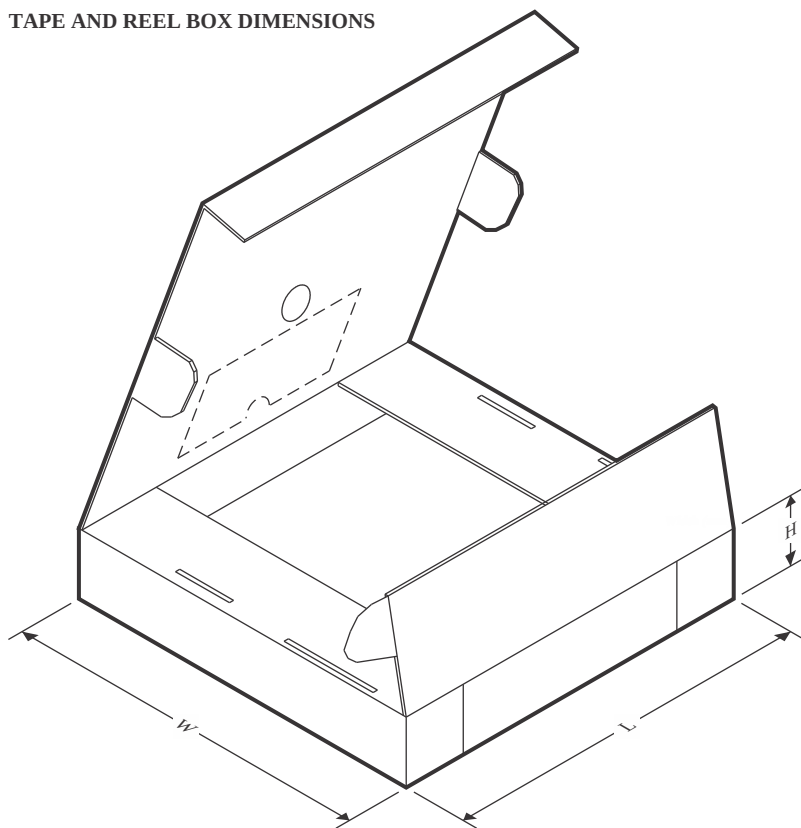
TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS63036YFGR	DSBGA	YFG	8	3000	180.0	8.4	1.2	2.0	0.7	4.0	8.0	Q1
TPS63036YFGT	DSBGA	YFG	8	250	180.0	8.4	1.2	2.0	0.7	4.0	8.0	Q1

TAPE AND REEL BOX DIMENSIONS

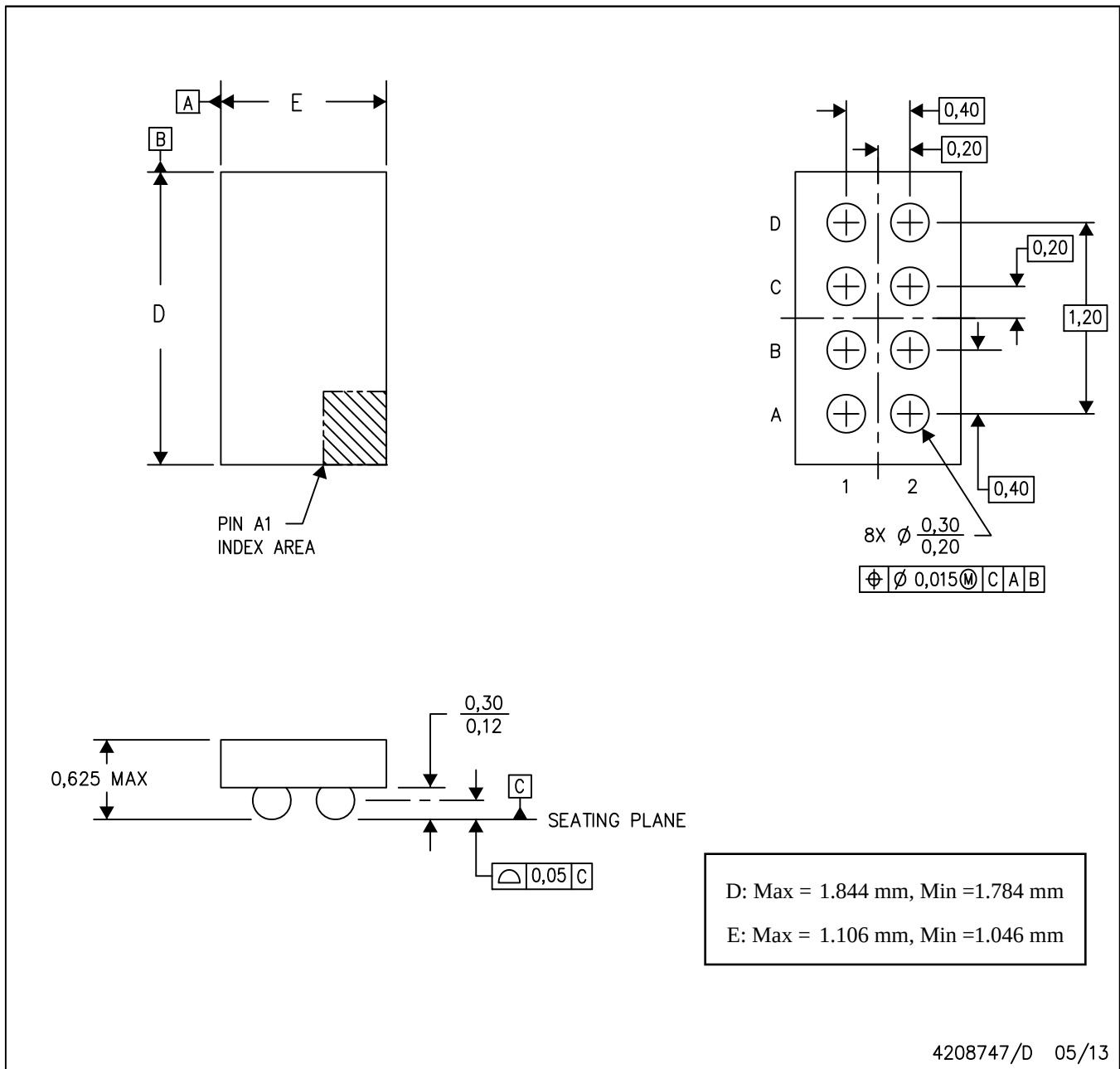


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS63036YFGR	DSBGA	YFG	8	3000	182.0	182.0	20.0
TPS63036YFGT	DSBGA	YFG	8	250	182.0	182.0	20.0

YFG (R-XBGA-N8)

DIE-SIZE BALL GRID ARRAY



- NOTES:
- A. All linear dimensions are in millimeters.
 - B. This drawing is subject to change without notice.
 - C. Die size package configuration.

重要通知和免责声明

TI“按原样”提供技术和可靠性数据（包括数据表）、设计资源（包括参考设计）、应用或其他设计建议、网络工具、安全信息和其他资源，不保证没有瑕疵且不做任何明示或暗示的担保，包括但不限于对适销性、某特定用途方面的适用性或不侵犯任何第三方知识产权的暗示担保。

这些资源可供使用 TI 产品进行设计的熟练开发人员使用。您将自行承担以下全部责任：(1) 针对您的应用选择合适的 TI 产品，(2) 设计、验证并测试您的应用，(3) 确保您的应用满足相应标准以及任何其他功能安全、信息安全、监管或其他要求。

这些资源如有变更，恕不另行通知。TI 授权您仅可将这些资源用于研发本资源所述的 TI 产品的相关应用。严禁以其他方式对这些资源进行复制或展示。您无权使用任何其他 TI 知识产权或任何第三方知识产权。您应全额赔偿因在这些资源的使用中对 TI 及其代表造成的任何索赔、损害、成本、损失和债务，TI 对此概不负责。

TI 提供的产品受 [TI 的销售条款](#) 或 [ti.com](#) 上其他适用条款/TI 产品随附的其他适用条款的约束。TI 提供这些资源并不会扩展或以其他方式更改 TI 针对 TI 产品发布的适用的担保或担保免责声明。

TI 反对并拒绝您可能提出的任何其他或不同的条款。

邮寄地址：Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
版权所有 © 2025，德州仪器 (TI) 公司