

具有 40V 内部 FET 开关且采用 SOT-23 封装的 LM2733 0.6MHz 和 1.6MHz 升压转换器

1 特性

- 40V DMOS FET 开关
- 1.6MHz (“X”)、0.6MHz (“Y”) 开关频率
- 低 $R_{DS(ON)}$ DMOS FET
- 高达 1A 的开关电流
- 宽输入电压范围：2.7V 至 14V
- 低关断电流 ($< 1\mu A$)
- 5 引脚 SOT-23 封装
- 使用微型电容器和电感器
- 逐周期电流限制
- 内部补偿

2 应用

- 白光 LED 电流源
- PDA 和掌上电脑
- 数码相机
- 便携式电话和游戏
- 本地升压稳压器

3 说明

LM2733 开关稳压器是在 1.6MHz (“X”选项) 和 600kHz (“Y”选项) 固定频率下工作的电流模式升压转换器。

通过使用 SOT-23 封装（凭借内部 1A 开关的极小功率损耗和使用小型电感器和电容器），可以实现业界最高的功率密度。40V 内部开关使这些解决方案非常适合升压至 16V 或更高的电压。

这些器件具有逻辑电平关断引脚，可用于降低静态电流并延长电池寿命。

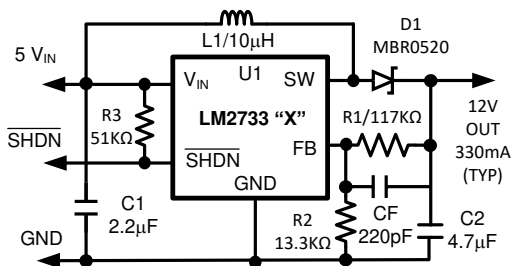
通过逐周期电流限制和热关断提供保护。内部补偿可简化设计并减少组件数量。

器件信息(1)

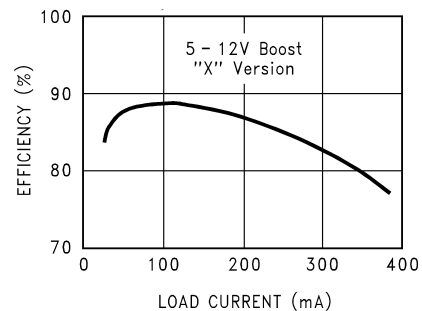
器件型号	封装	封装尺寸（标称值）
LM2733	SOT-23 (5)	2.90mm × 1.60mm

(1) 如需了解所有可用封装，请参阅数据表末尾的可订购产品附录。

典型应用电路



效率与负载电流间的关系



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4 修订历史记录

注：之前版本的页码可能与当前版本有所不同。

Changes from Revision F (December 2014) to Revision G Page

- 已更改 典型应用电路图像，以更正异常的连接器线路。 1

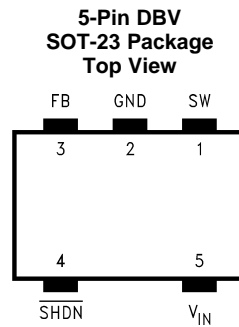
Changes from Revision E (April 2013) to Revision F Page

- 已添加 引脚配置和功能 部分、ESD 额定值 表、特性 说明 部分，器件功能模式，应用和实施部分，电源相关建议部分，布局部分，器件和文档支持部分以及机械、封装和可订购信息部分 1

Changes from Revision D (April 2013) to Revision E Page

- Changed layout of National Semiconductor Data Sheet to TI format 11

5 Pin Configuration and Functions



Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
SW	1	O	Drain of the internal FET switch.
GND	2	GND	Analog and power ground.
FB	3	I	Feedback point that connects to external resistive divider.
SHDN	4	I	Shutdown control input. Connect to VIN if this feature is not used.
VIN	5	I	Analog and power input.

6 Specifications

6.1 Absolute Maximum Ratings⁽¹⁾⁽²⁾

	MIN	MAX	UNIT
Input supply voltage (VIN)	−0.4	14.5	V
FB pin voltage	−0.4	6	V
SW pin voltage	−0.4	40	V
SHDN pin voltage	−0.4	VIN + 0.3	V
Power dissipation ⁽³⁾	Internally Limited		
Lead temperature (soldering, 5 sec.)		300	°C
Storage temperature, Tstg	−65	150	°C

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the component may occur. Electrical specifications do not apply when operating the device outside of the limits set forth under the operating ratings which specify the intended range of operating conditions.
- (2) If Military/Aerospace specified devices are required, contact the Texas Instruments Sales Office/ Distributors for availability and specifications.
- (3) The maximum power dissipation which can be safely dissipated for any application is a function of the maximum junction temperature, TJ(MAX) = 125°C, the junction-to-ambient thermal resistance for the SOT-23 package, RθJA = 210°C/W, and the ambient temperature, TA. The maximum allowable power dissipation at any ambient temperature for designs using this device can be calculated using the formula:
- $$P_{(MAX)} = \frac{T_J(MAX) - T_A}{\theta_{JA}} = \frac{125 - T_A}{265}$$
- If power dissipation exceeds the maximum specified above, the internal thermal protection circuitry protects the device by reducing the output voltage as required to maintain a safe junction temperature.

6.2 ESD Ratings

			VALUE	UNIT
V(ESD)	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins ⁽¹⁾	±2000	V
		Machine model	±200	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

	MIN	MAX	UNIT
Input supply voltage (VIN)	2.7	14	V
SHDN pin voltage	0	VIN	V
Junction temperature	–40	125	°C

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		LM2733	UNIT
		DBV (SOT-23)	
		5 PINS	
RθJA	Junction-to-ambient thermal resistance	210	°C/W
RθJC(top)	Junction-to-case (top) thermal resistance	122	°C/W
RθJB	Junction-to-board thermal resistance	38.4	°C/W
ψJT	Junction-to-top characterization parameter	12.8	°C/W
ψJB	Junction-to-board characterization parameter	37.5	°C/W
RθJC(bot)	Junction-to-case (bottom) thermal resistance	n/a	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) SPRA953 application report.

6.5 Electrical Characteristics

Unless otherwise specified: VIN = 5 V, VSHDN = 5 V, IL = 0 A, TJ = 25°C.

PARAMETER		TEST CONDITIONS	MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	UNIT
VIN	Input voltage	–40°C ≤ TJ ≤ +125°C	2.7		14	V
ISW	Switch current limit	See ⁽³⁾	1	1.5		A
RDS(ON)	Switch ON resistance	ISW = 100 mA		500	650	mΩ
SHDNTH	Shutdown threshold	Device ON, –40°C ≤ TJ ≤ +125°C	1.5			V
		Device OFF, –40°C ≤ TJ ≤ +125°C			0.50	
ISHDN	Shutdown pin bias current	VSHDN = 0		0		μA
		VSHDN = 5 V		0		
		VSHDN = 5 V, –40°C ≤ TJ ≤ +125°C			2	
VFB	Feedback pin reference voltage	VIN = 3 V		1.230		V
		VIN = 3 V, –40°C ≤ TJ ≤ +125°C	1.205		1.255	
IFB	Feedback pin bias current	VFB = 1.23 V		60		nA
IQ	Quiescent current	VSHDN = 5 V, Switching "X"		2.1		mA
		VSHDN = 5 V, Switching "X", –40°C ≤ TJ ≤ +125°C			3	
		VSHDN = 5 V, Switching "Y"		1.1		
		VSHDN = 5 V, Switching "Y", –40°C ≤ TJ ≤ +125°C			2	
		VSHDN = 5 V, Not Switching		400		μA
		VSHDN = 5 V, Not Switching, –40°C ≤ TJ ≤ +125°C			500	
		VSHDN = 0		0.024	1	
ΔVFB/ΔVIN	FB voltage line regulation	2.7 V ≤ VIN ≤ 14 V		0.02		%/V

(1) Limits are specified by testing, statistical correlation, or design.

(2) Typical values are derived from the mean value of a large quantity of samples tested during characterization and represent the most likely expected value of the parameter at room temperature.

(3) Switch current limit is dependent on duty cycle (see [Typical Characteristics](#)). Limits shown are for duty cycles ≤ 50%.

Electrical Characteristics (continued)

Unless otherwise specified: $V_{IN} = 5\text{ V}$, $V_{SHDN} = 5\text{ V}$, $I_L = 0\text{ A}$, $T_J = 25^\circ\text{C}$.

PARAMETER		TEST CONDITIONS	MIN ⁽¹⁾	TYP ⁽²⁾	MAX ⁽¹⁾	UNIT
F_{SW}	Switching frequency	"X" Option		1.6		MHz
		"X" Option, $-40^\circ\text{C} \leq T_J \leq +125^\circ\text{C}$	1.15		1.85	
		"Y" Option		0.60		
		"Y" Option, $-40^\circ\text{C} \leq T_J \leq +125^\circ\text{C}$	0.40		0.8	
D_{MAX}	Maximum duty cycle	"X" Option		93%		
		"X" Option, $-40^\circ\text{C} \leq T_J \leq +125^\circ\text{C}$	87%			
		"Y" Option		96%		
		"Y" Option, $-40^\circ\text{C} \leq T_J \leq +125^\circ\text{C}$	93%			
I_L	Switch leakage	Not Switching $V_{SW} = 5\text{ V}$			1	μA

6.6 Typical Characteristics

Unless otherwise specified: $V_{IN} = 5\text{ V}$, $\overline{\text{SHDN}}$ pin is tied to V_{IN} .

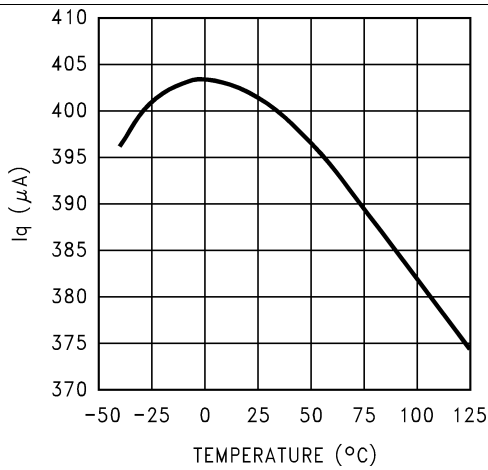


Figure 1. I_q V_{IN} (Active) vs Temperature - "X"

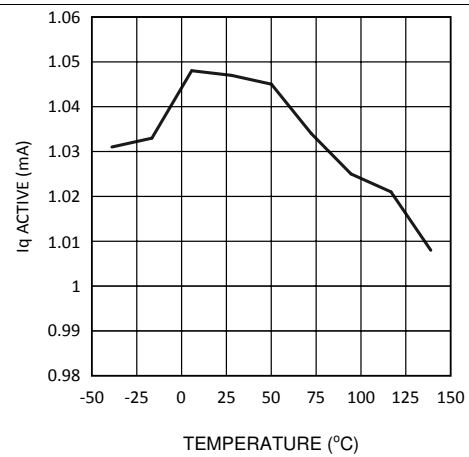


Figure 2. I_q V_{IN} (Active) vs Temperature - "Y"

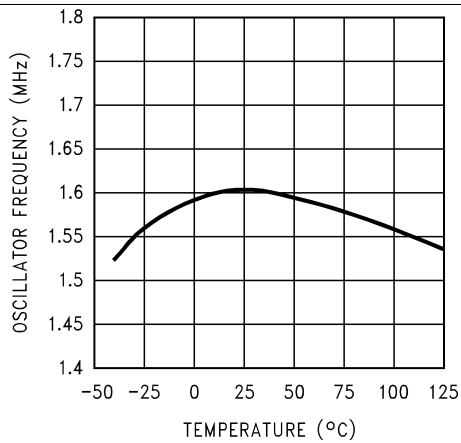


Figure 3. Oscillator Frequency vs Temperature - "X"

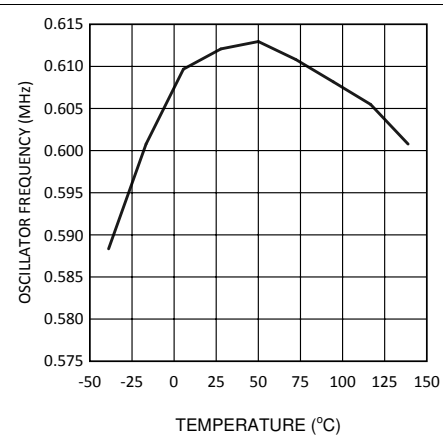


Figure 4. Oscillator Frequency vs Temperature - "Y"

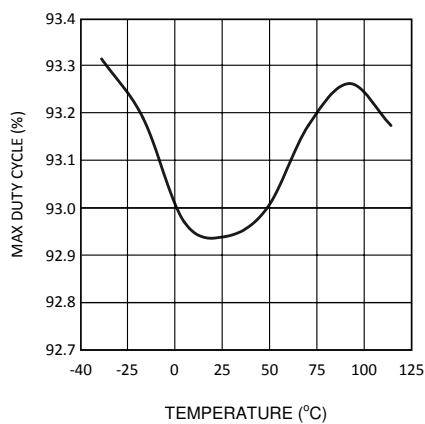


Figure 5. Max. Duty Cycle vs Temperature - "X"

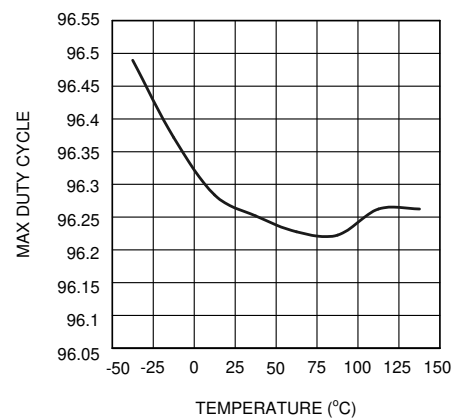


Figure 6. Max. Duty Cycle vs Temperature - "Y"

Typical Characteristics (continued)

Unless otherwise specified: $V_{IN} = 5\text{ V}$, $\overline{\text{SHDN}}$ pin is tied to V_{IN} .

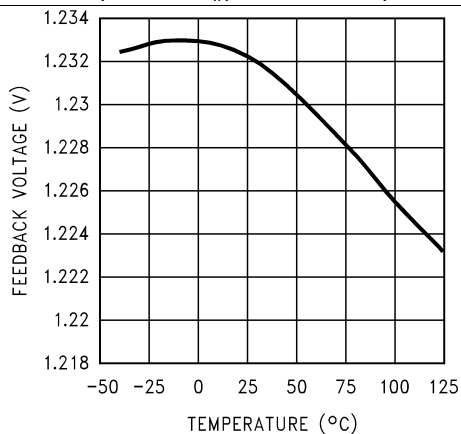


Figure 7. Feedback Voltage vs Temperature

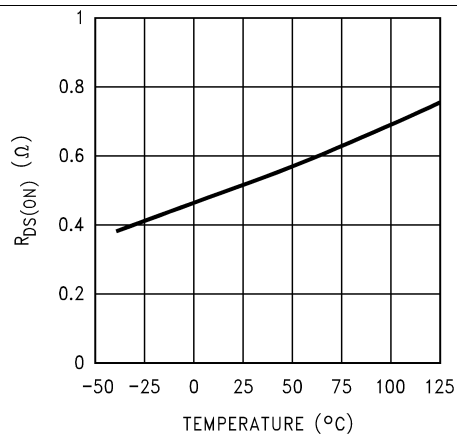


Figure 8. $R_{DS(ON)}$ vs Temperature

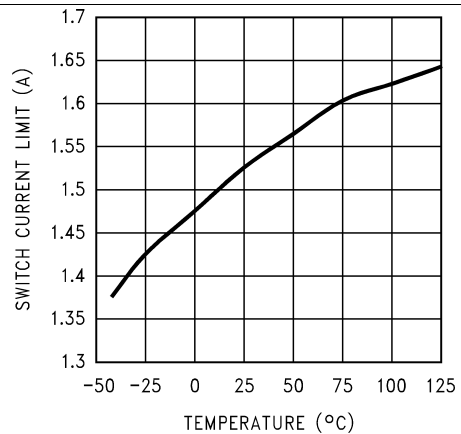


Figure 9. Current Limit vs Temperature

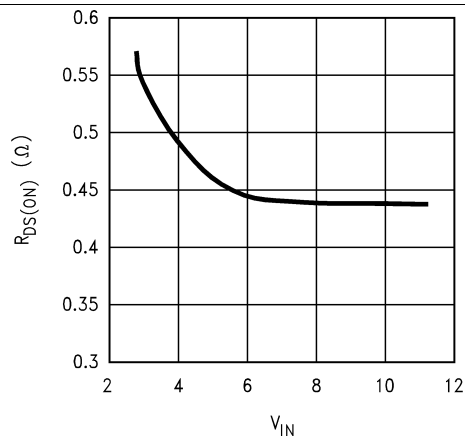


Figure 10. $R_{DS(ON)}$ vs V_{IN}

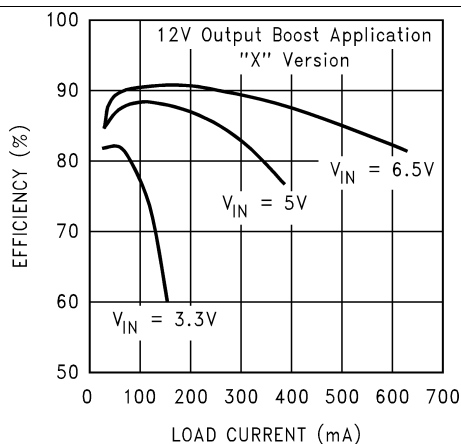


Figure 11. Efficiency vs Load Current ($V_{OUT} = 12\text{ V}$) - "X"

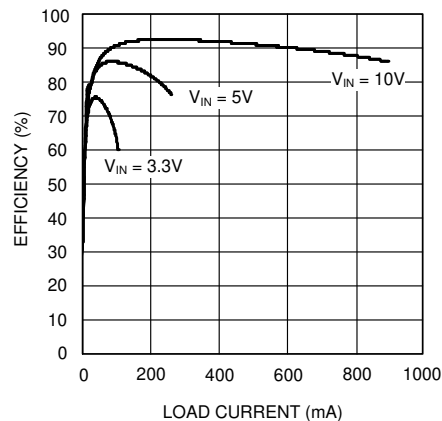


Figure 12. Efficiency vs Load Current ($V_{OUT} = 15\text{ V}$) - "X"

Typical Characteristics (continued)

Unless otherwise specified: $V_{IN} = 5\text{ V}$, $\overline{\text{SHDN}}$ pin is tied to V_{IN} .

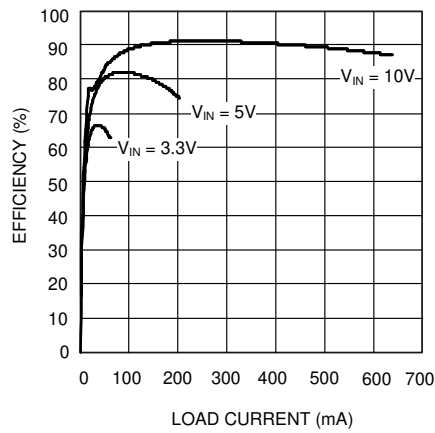


Figure 13. Efficiency vs Load Current ($V_{OUT} = 20\text{ V}$) - "X"

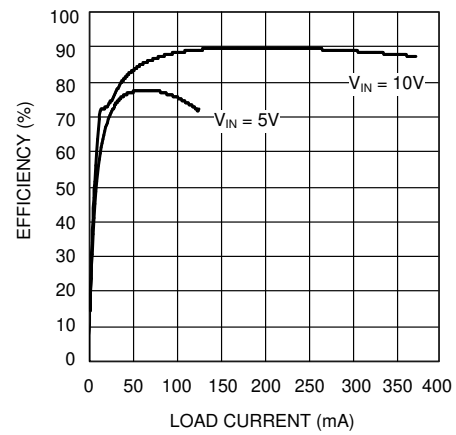


Figure 14. Efficiency vs Load Current ($V_{OUT} = 25\text{ V}$) - "X"

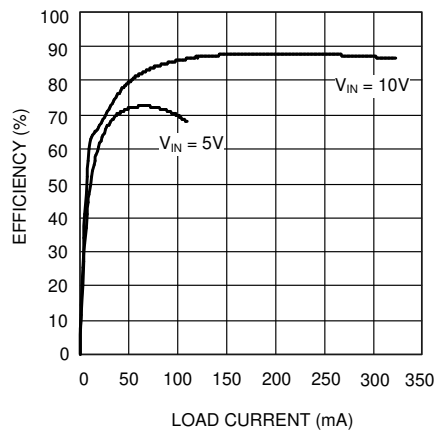


Figure 15. Efficiency vs Load Current ($V_{OUT} = 30\text{ V}$) - "X"

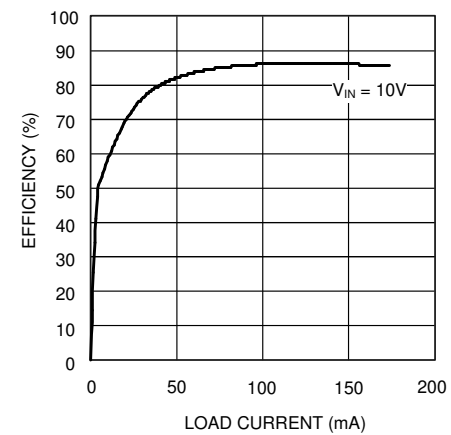


Figure 16. Efficiency vs Load Current ($V_{OUT} = 35\text{ V}$) - "X"

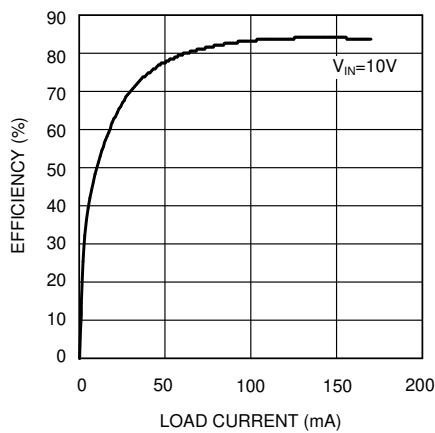


Figure 17. Efficiency vs Load Current ($V_{OUT} = 40\text{ V}$) - "X"

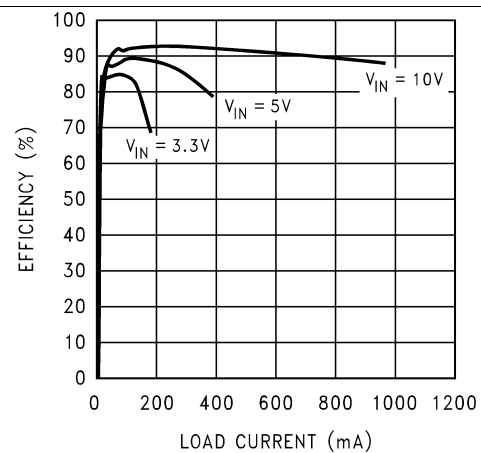


Figure 18. Efficiency vs Load ($V_{OUT} = 15\text{ V}$) - "Y"

Typical Characteristics (continued)

Unless otherwise specified: $V_{IN} = 5\text{ V}$, $\overline{\text{SHDN}}$ pin is tied to V_{IN} .

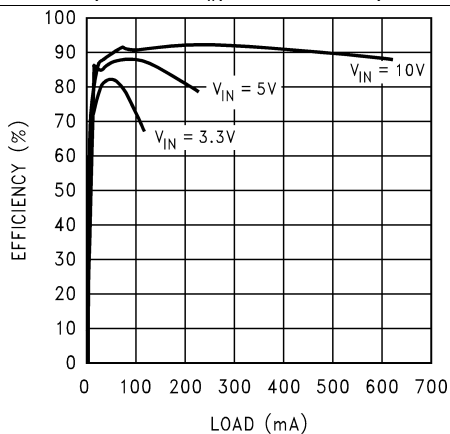


Figure 19. Efficiency vs Load ($V_{OUT} = 20\text{ V}$) - "Y"

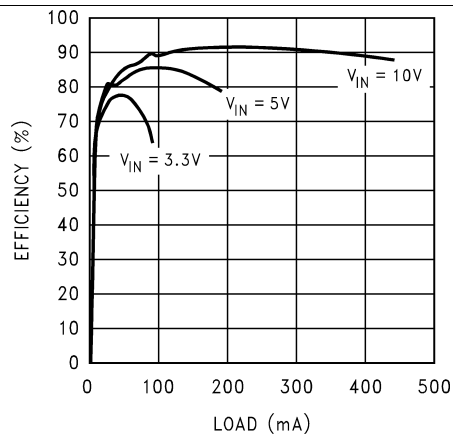


Figure 20. Efficiency vs Load ($V_{OUT} = 25\text{ V}$) - "Y"

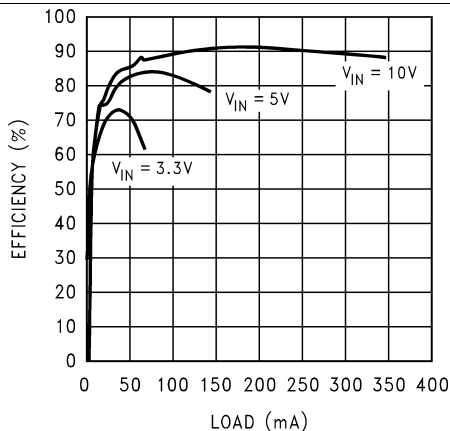


Figure 21. Efficiency vs Load ($V_{OUT} = 30\text{ V}$) - "Y"

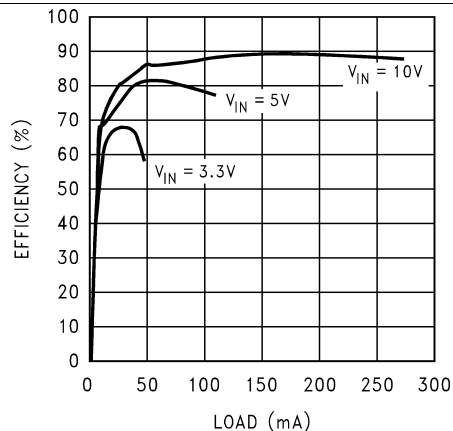


Figure 22. Efficiency vs Load ($V_{OUT} = 35\text{ V}$) - "Y"

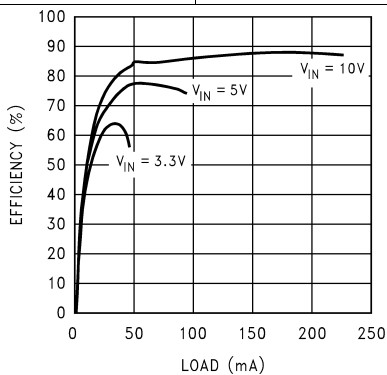


Figure 23. Efficiency vs Load ($V_{OUT} = 40\text{ V}$) - "Y"

7 Detailed Description

7.1 Overview

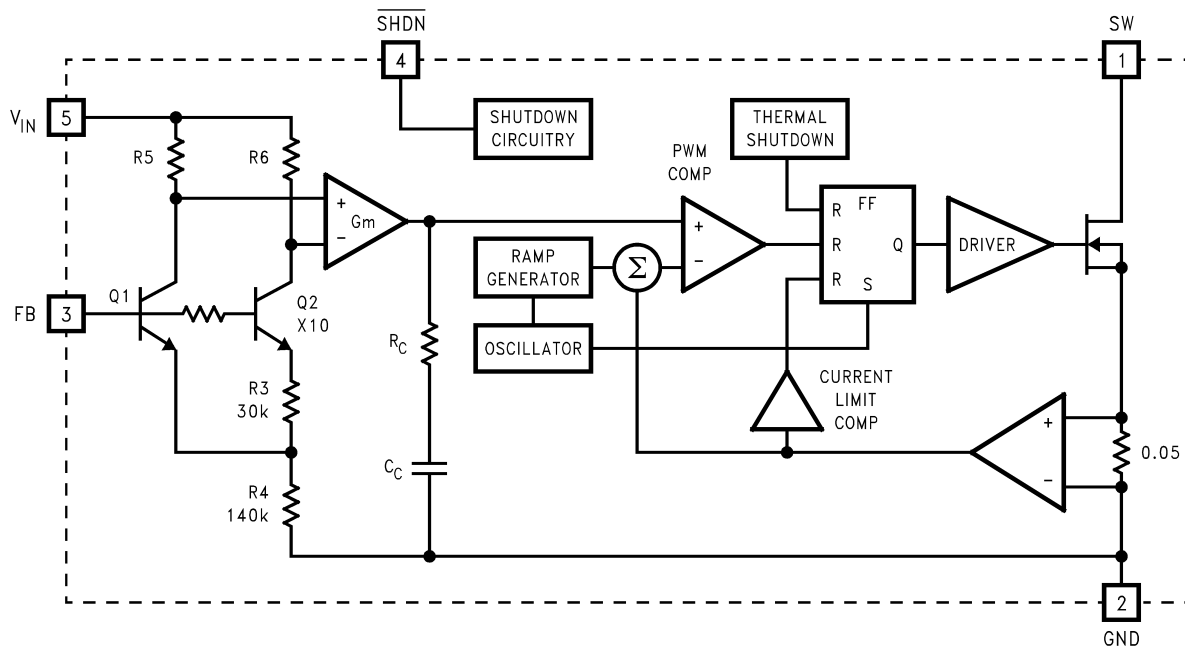
The LM2733 device is a switching converter IC that operates at a fixed frequency (0.6 or 1.6 MHz) using current-mode control for fast transient response over a wide input voltage range and incorporate pulse-by-pulse current limiting protection. Because this is current mode control, a 50 mΩ sense resistor in series with the switch FET is used to provide a voltage (which is proportional to the FET current) to both the input of the pulse width modulation (PWM) comparator and the current limit amplifier.

At the beginning of each cycle, the S-R latch turns on the FET. As the current through the FET increases, a voltage (proportional to this current) is summed with the ramp coming from the ramp generator and then fed into the input of the PWM comparator. When this voltage exceeds the voltage on the other input (coming from the Gm amplifier), the latch resets and turns the FET off. Since the signal coming from the Gm amplifier is derived from the feedback (which samples the voltage at the output), the action of the PWM comparator constantly sets the correct peak current through the FET to keep the output voltage in regulation.

Q1 and Q2 along with R3 - R6 form a bandgap voltage reference used by the IC to hold the output in regulation. The currents flowing through Q1 and Q2 will be equal, and the feedback loop will adjust the regulated output to maintain this. Because of this, the regulated output is always maintained at a voltage level equal to the voltage at the FB node "multiplied up" by the ratio of the output resistive divider.

The current limit comparator feeds directly into the flip-flop, that drives the switch FET. If the FET current reaches the limit threshold, the FET is turned off and the cycle terminated until the next clock pulse. The current limit input terminates the pulse regardless of the status of the output of the PWM comparator.

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 Switching Frequency

The LM2733 device is provided with two switching frequencies: the "X" version is typically 1.6 MHz, while the "Y" version is typically 600 kHz. The best frequency for a specific application must be determined based on the tradeoffs involved. See [Switching Frequency](#) in the [Detailed Design Procedure](#) section.

7.4 Device Functional Modes

7.4.1 Shutdown Pin Operation

The device is turned off by pulling the shutdown pin low. If this function is not going to be used, tie the pin directly to V_{IN} . If the SHDN function is needed, a pullup resistor must be used to V_{IN} (approximately 50 k to 100 k Ω recommended). The SHDN pin must not be left unterminated.

8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The LM2733 device is a high frequency switching boost regulator that offers small size and high power conversion efficiency. The "X" version of the part operates at 1.6 MHz switching frequency and the "Y" version at 600 kHz.

The LM2733 device targets applications with high output voltages and uses a high voltage FET allowing switch currents up to 1 A. The LM2731 device is similar to the LM2733 device but has a lower voltage FET allowing switch currents up to 1.8 A.

8.2 Typical Application

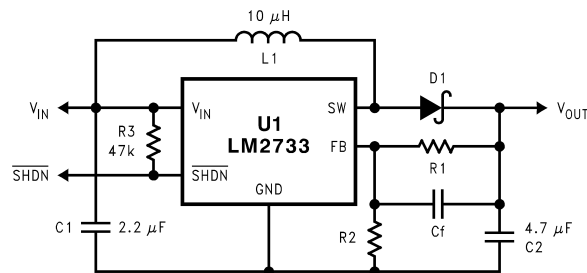


Figure 24. Basic Application Circuit

8.2.1 Design Requirements

Table 1. Circuit Configurations

COMPONENT	LM2733-X	LM2733-X	LM2733-Y
	LOW VOLTAGE 5-12 V 330 mA typical	HIGH VOLTAGE 20 V 170 mA typical	HIGH VOLTAGE 30 V 110 mA typical
R1	117 K	205 K	309 K
R2	13.3 K	13.3 K	13.3 K
Cf	220 pF	120 pF	82 pF
D1	MBR0520	MBR0530	MBR0540

8.2.2 Detailed Design Procedure

8.2.2.1 Selecting the External Capacitors

The best capacitors for use with the LM2733 device are multi-layer ceramic capacitors. They have the lowest ESR (equivalent series resistance) and highest resonance frequency which makes them optimum for use with high frequency switching converters.

When selecting a ceramic capacitor, use only X5R and X7R dielectric types. Other types such as Z5U and Y5F have such severe loss of capacitance due to effects of temperature variation and applied voltage, they may provide as little as 20% of rated capacitance in many typical applications. Always consult capacitor manufacturer's data curves before selecting a capacitor. High-quality ceramic capacitors can be obtained from Taiyo-Yuden, AVX, and Murata.

8.2.2.2 Selecting the Output Capacitor

A single ceramic capacitor of value 4.7 μF to 10 μF provides sufficient output capacitance for most applications. For output voltages below 10 V, a 10- μF capacitance is required. If larger amounts of capacitance are desired for improved line support and transient response, tantalum capacitors can be used in parallel with the ceramics. Aluminum electrolytics with ultra-low ESR such as Sanyo Oscon can be used, but are usually prohibitively expensive. Typical Al electrolytic capacitors are not suitable for switching frequencies above 500 kHz due to significant ringing and temperature rise due to self-heating from ripple current. An output capacitor with excessive ESR can also reduce phase margin and cause instability.

8.2.2.3 Selecting the Input Capacitor

An input capacitor is required to serve as an energy reservoir for the current which must flow into the coil each time the switch turns ON. This capacitor must have extremely low ESR, so ceramic is the best choice. TI recommends a nominal value of 2.2 μF , but larger values can be used. Because this capacitor reduces the amount of voltage ripple detected at the input pin, it also reduces the amount of EMI passed back along that line to other circuitry.

8.2.2.4 Feedforward Compensation

Although internally compensated, the feedforward capacitor C_f is required for stability (see [Figure 24](#)). Adding this capacitor puts a zero in the loop response of the converter. Without it, the regulator loop can oscillate. The recommended frequency for the zero f_z is approximately 8 kHz. C_f can be calculated using the formula:

$$C_f = 1 / (2 \times \pi \times R_1 \times f_z) \quad (1)$$

8.2.2.5 Selecting Diodes

The external diode used in the typical application should be a Schottky diode. If the switch voltage is less than 15 V, a 20-V diode such as the MBR0520 is recommended. If the switch voltage is between 15 V and 25 V, TI recommends a 30-V diode such as the MBR0530. If the switch voltage exceeds 25 V, a 40-V diode such as the MBR0540 should be used.

The MBR05XX series of diodes are designed to handle a maximum average current of 0.5 A. For applications exceeding 0.5 A average but less than 1 A, a Microsemi UPS5817 can be used.

8.2.2.6 Setting the Output Voltage

The output voltage is set using the external resistors R_1 and R_2 (see [Figure 24](#)). A value of approximately 13.3 k Ω is recommended for R_2 to establish a divider current of approximately 92 μA . R_1 is calculated using the formula:

$$R_1 = R_2 \times (V_{\text{OUT}}/1.23 - 1) \quad (2)$$

8.2.2.7 Switching Frequency

The device options provide for two fixed frequency operating conditions 1.6 MHz, and 600 kHz. Chose the operating frequency required noting the following trade-offs:

Higher switching frequency means the inductors and capacitors can be made smaller and cheaper for a given output voltage and current. The down side is that efficiency is slightly lower because the fixed switching losses occur more frequently and become a larger percentage of total power loss. EMI is typically worse at higher switching frequencies because more EMI energy will be seen in the higher frequency spectrum where most circuits are more sensitive to such interference.

8.2.2.8 Duty Cycle

The maximum duty cycle of the switching regulator determines the maximum boost ratio of output-to-input voltage that the converter can attain in continuous mode of operation. The duty cycle for a given boost application is defined as:

$$\text{Duty Cycle} = \frac{V_{\text{OUT}} + V_{\text{DIODE}} - V_{\text{IN}}}{V_{\text{OUT}} + V_{\text{DIODE}} - V_{\text{SW}}} \quad (3)$$

This applies for continuous mode operation.

The equation shown for calculating duty cycle incorporates terms for the FET switch voltage and diode forward voltage. The actual duty cycle measured in operation will also be affected slightly by other power losses in the circuit such as wire losses in the inductor, switching losses, and capacitor ripple current losses from self-heating. Therefore, the actual (effective) duty cycle measured may be slightly higher than calculated to compensate for these power losses. A good approximation for effective duty cycle is :

$$DC \text{ (eff)} = (1 - \text{Efficiency} \times (V_{IN}/V_{OUT})) \quad (4)$$

Where the efficiency can be approximated from the curves provided.

8.2.2.9 Inductance Value

The first question we are usually asked is: “How small can I make the inductor?” (because they are the largest sized component and usually the most costly). The answer is not simple and involves tradeoffs in performance. Larger inductors mean less inductor ripple current, which typically means less output voltage ripple (for a given size of output capacitor). Larger inductors also mean more load power can be delivered because the energy stored during each switching cycle is:

$$E = L/2 \times (I_p)^2 \quad (5)$$

Where “ I_p ” is the peak inductor current. An important point to observe is that the LM2733 device will limit its switch current based on peak current. This means that since I_p (maximum) is fixed, increasing L will increase the maximum amount of power available to the load. Conversely, using too little inductance may limit the amount of load current which can be drawn from the output.

Best performance is usually obtained when the converter is operated in “continuous” mode at the load current range of interest, typically giving better load regulation and less output ripple. Continuous operation is defined as not allowing the inductor current to drop to zero during the cycle. It should be noted that all boost converters shift over to discontinuous operation as the output load is reduced far enough, but a larger inductor stays “continuous” over a wider load current range.

To better understand these tradeoffs, a typical application circuit (5V to 12V boost with a 10 μH inductor) will be analyzed. We will assume:

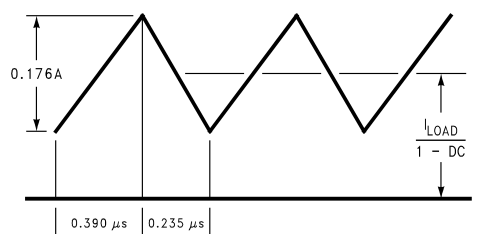
$$V_{IN} = 5 \text{ V}, V_{OUT} = 12 \text{ V}, V_{DIODE} = 0.5 \text{ V}, V_{SW} = 0.5 \text{ V}$$

Since the frequency is 1.6 MHz (nominal), the period is approximately 0.625 μs . The duty cycle will be 62.5%, which means the ON time of the switch is 0.390 μs . It should be noted that when the switch is ON, the voltage across the inductor is approximately 4.5 V.

Using the equation:

$$V = L (di/dt) \quad (6)$$

We can then calculate the di/dt rate of the inductor which is found to be 0.45 A/ μs during the ON time. Using these facts, we can then show what the inductor current will look like during operation:



**Figure 25. 10- μH Inductor Current,
5-V – 12-V Boost (LM2733X)**

During the 0.390 μs ON time, the inductor current ramps up 0.176 A and ramps down an equal amount during the OFF time. This is defined as the inductor “ripple current”. It can also be seen that if the load current drops to about 33 mA, the inductor current will begin touching the zero axis which means it will be in discontinuous mode. A similar analysis can be performed on any boost converter, to make sure the ripple current is reasonable and continuous operation will be maintained at the typical load current values.

8.2.2.10 Maximum Switch Current

The maximum FET switch current available before the current limiter cuts in is dependent on duty cycle of the application. This is illustrated in the graphs below which show both the typical and specified values of switch current for both the "X" and "Y" versions as a function of effective (actual) duty cycle:

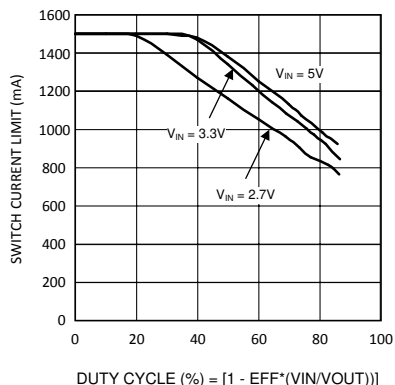


Figure 26. Switch Current Limit vs Duty Cycle - "X"

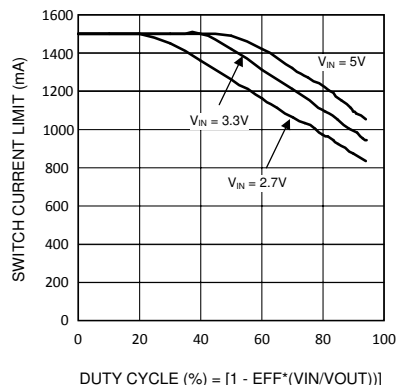


Figure 27. Switch Current Limit vs Duty Cycle - "Y"

8.2.2.11 Calculating Load Current

As shown in the figure which depicts inductor current, the load current is related to the average inductor current by the relation:

$$I_{\text{LOAD}} = I_{\text{IND}}(\text{AVG}) \times (1 - \text{DC}) \quad (7)$$

Where "DC" is the duty cycle of the application. The switch current can be found by:

$$I_{\text{SW}} = I_{\text{IND}}(\text{AVG}) + \frac{1}{2} (I_{\text{RIPPLE}}) \quad (8)$$

Inductor ripple current is dependent on inductance, duty cycle, input voltage and frequency:

$$I_{\text{RIPPLE}} = \text{DC} \times (V_{\text{IN}} - V_{\text{SW}}) / (f \times L) \quad (9)$$

combining all terms, we can develop an expression which allows the maximum available load current to be calculated:

$$I_{\text{LOAD}}(\text{max}) = (1 - \text{DC}) \times (I_{\text{SW}}(\text{max}) - \text{DC} (V_{\text{IN}} - V_{\text{SW}})) / 2fL \quad (10)$$

The equation shown to calculate maximum load current takes into account the losses in the inductor or turn-OFF switching losses of the FET and diode. For actual load current in typical applications, we took bench data for various input and output voltages for both the "X" and "Y" versions of the LM2733 device and displayed the maximum load current available for a typical device in graph form:

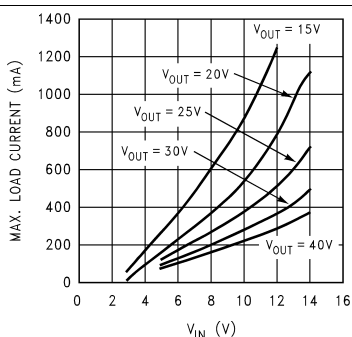


Figure 28. Max. Load Current vs V_{IN} - "X"

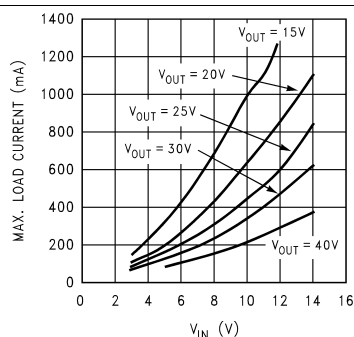


Figure 29. Max. Load Current vs V_{IN} - "Y"

8.2.2.12 Design Parameters V_{SW} and I_{SW}

The value of the FET "ON" voltage (referred to as V_{SW} in the equations) is dependent on load current. A good approximation can be obtained by multiplying the "ON Resistance" of the FET times the average inductor current.

FET on resistance increases at V_{IN} values below 5 V, since the internal N-FET has less gate voltage in this input voltage range (see [Typical Characteristics](#)). Above $V_{IN} = 5$ V, the FET gate voltage is internally clamped to 5 V.

The maximum peak switch current the device can deliver is dependent on duty cycle. The minimum value is specified to be > 1 A at duty cycle below 50%. For higher duty cycles, see [Typical Characteristics](#).

8.2.2.13 Thermal Considerations

At higher duty cycles, the increased ON time of the FET means the maximum output current will be determined by power dissipation within the LM2733 FET switch. The switch power dissipation from ON-state conduction is calculated by:

$$P_{(SW)} = DC \times I_{IND(AVE)}^2 \times R_{DS(ON)} \quad (11)$$

There will be some switching losses as well, so some derating needs to be applied when calculating IC power dissipation.

8.2.2.14 Minimum Inductance

In some applications where the maximum load current is relatively small, it may be advantageous to use the smallest possible inductance value for cost and size savings. The converter will operate in discontinuous mode in such a case.

The minimum inductance should be selected such that the inductor (switch) current peak on each cycle does not reach the 1-A current limit maximum. To understand how to do this, an example will be presented.

In the example, the LM2733X will be used (nominal switching frequency 1.6 MHz, minimum switching frequency 1.15 MHz). This means the maximum cycle period is the reciprocal of the minimum frequency:

$$T_{ON(max)} = 1/1.15M = 0.870 \mu s \quad (12)$$

We will assume the input voltage is 5 V, $V_{OUT} = 12$ V, $V_{SW} = 0.2$ V, $V_{DIODE} = 0.3$ V. The duty cycle is:

Duty Cycle = 60.3%

Therefore, the maximum switch ON time is 0.524 μs . An inductor should be selected with enough inductance to prevent the switch current from reaching 1A in the 0.524 μs ON time interval (see below):

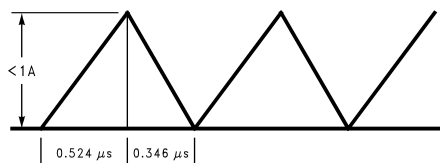


Figure 30. Discontinuous Design, 5V–12V Boost (LM2733X)

The voltage across the inductor during ON time is 4.8V. Minimum inductance value is found by:

$$V = L \times di/dt, L = V \times (dt/di) = 4.8 (0.524\mu/1) = 2.5 \mu H \quad (13)$$

In this case, a 2.7 μH inductor could be used assuming it provided at least that much inductance up to the 1A current value. This same analysis can be used to find the minimum inductance for any boost application. Using the slower switching "Y" version requires a higher amount of minimum inductance because of the longer switching period.

8.2.2.15 Inductor Suppliers

Some of the recommended suppliers of inductors for this product include, but not limited to are Sumida, Coilcraft, Panasonic, TDK and Murata. When selecting an inductor, make certain that the continuous current rating is high enough to avoid saturation at peak currents. A suitable core type must be used to minimize core (switching) losses, and wire power losses must be considered when selecting the current rating.

8.2.3 Application Curves

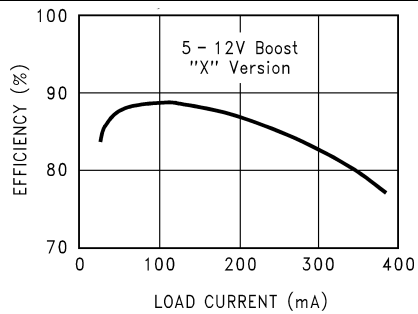


Figure 31. Efficiency vs. Load Current (5-12V, X-version)

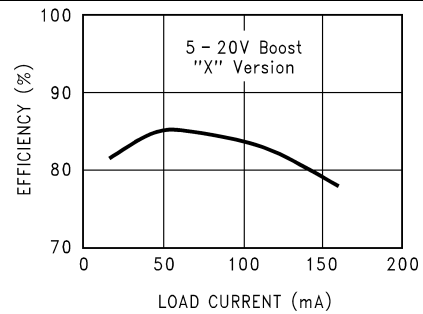


Figure 32. Efficiency vs. Load Current (5-20V X-version)

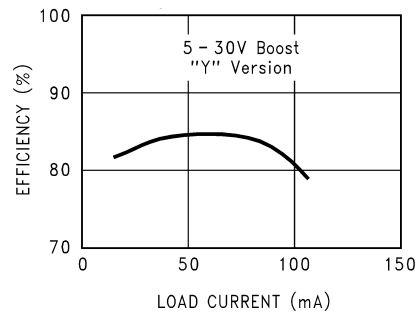


Figure 33. Efficiency vs. Load Current (5 - 30V Y-version)

9 Power Supply Recommendations

The device input voltage range is 2.7 V to 14 V.

The voltage on the shutdown pin should not exceed the voltage on the VIN pin. For applications that do not require a shutdown function the shutdown pin may be connected to the VIN pin. In this case a 47-K Ω resistor is recommended to be connected between these pins.

10 Layout

10.1 Layout Guidelines

High frequency switching regulators require very careful layout of components in order to get stable operation and low noise. All components must be as close as possible to the LM2733 device. It is recommended that a 4-layer PCB be used so that internal ground planes are available.

Some additional guidelines to be observed:

1. Keep the path between L1, D1, and C2 extremely short. Parasitic trace inductance in series with D1 and C2 will increase noise and ringing.
2. The feedback components R1, R2 and CF must be kept close to the FB pin of U1 to prevent noise injection on the FB pin trace.
3. If internal ground planes are available (recommended) use vias to connect directly to ground at pin 2 of U1, as well as the negative sides of capacitors C1 and C2.

10.2 Layout Example

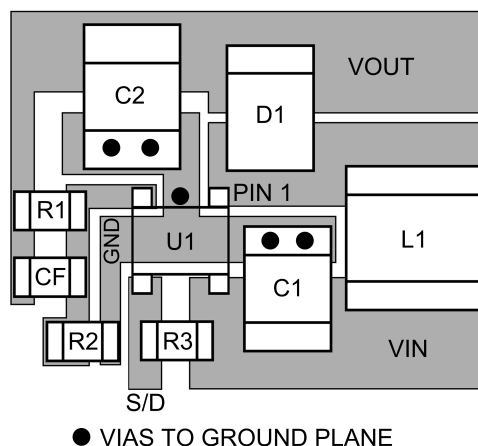


Figure 34. Recommended PCB Component Layout

11 器件和文档支持

11.1 商标

All trademarks are the property of their respective owners.

11.2 静电放电警告



这些装置包含有限的内置 ESD 保护。存储或装卸时，应将导线一起截短或将装置放置于导电泡棉中，以防止 MOS 门极遭受静电损伤。

11.3 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 机械、封装和可订购信息

以下页面包含机械、封装和可订购信息。这些信息是指定器件的最新可用数据。数据如有变更，恕不另行通知，且不会对此文档进行修订。如需获取此数据表的浏览器版本，请查阅左侧的导航栏。

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
LM2733XMF/NOPB	Active	Production	SOT-23 (DBV) 5	1000 SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	S52A
LM2733XMF/NOPB	Active	Production	SOT-23 (DBV) 5	3000 LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	S52A
LM2733YMF/NOPB	Active	Production	SOT-23 (DBV) 5	1000 SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	S52B
LM2733YMF/NOPB	Active	Production	SOT-23 (DBV) 5	3000 LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	S52B

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LM2733XMF/NOPB	SOT-23	DBV	5	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LM2733XMF/NOPB	SOT-23	DBV	5	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LM2733YMF/NOPB	SOT-23	DBV	5	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LM2733YMF/NOPB	SOT-23	DBV	5	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LM2733XMF/NOPB	SOT-23	DBV	5	1000	210.0	185.0	35.0
LM2733XMF/NOPB	SOT-23	DBV	5	3000	210.0	185.0	35.0
LM2733YMF/NOPB	SOT-23	DBV	5	1000	210.0	185.0	35.0
LM2733YMF/NOPB	SOT-23	DBV	5	3000	210.0	185.0	35.0



NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. Reference JEDEC MO-178.
4. Body dimensions do not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.25 mm per side.
5. Support pin may differ or may not be present.

EXAMPLE BOARD LAYOUT

DBV0005A

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:15X



SOLDER MASK DETAILS

4214839/K 08/2024

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

DBV0005A

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE:15X

4214839/K 08/2024

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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