











#### LMP7701, LMP7702, LMP7704

SNOSAI9I - SEPTEMBER 2005 - REVISED NOVEMBER 2015

# LMP770x Precision, CMOS Input, RRIO, Wide Supply Range Amplifiers

#### **Features**

Unless Otherwise Noted, Typical Values at  $V_S = 5 \text{ V}$ 

Input Offset Voltage (LMP7701): ±200-µV (Maximum)

Input Offset Voltage (LMP7702/LMP7704): ±220μV (Maximum)

Input Bias Current: ±200 fA Input Bias Current: ±200 fA Input Voltage Noise: 9 nV/√Hz

CMRR: 130 dB

Open-Loop Gain: 130 dB

Temperature Range: -40°C to 125°C

Unity-Gain Bandwidth: 2.5 MHz Supply Current (LMP7701): 715 µA

Supply Current (LMP7702): 1.5 mA

Supply Current (LMP7704): 2.9 mA

Supply Voltage Range: 2.7 V to 12 V

Rail-to-Rail Input and Output

## **Applications**

- High Impedance Sensor Interface
- **Battery-Powered Instrumentation**
- **High Gain Amplifiers**
- **DAC Buffer**
- Instrumentation Amplifier
- Active Filters

## 3 Description

The LMP770x are single, dual, and quad low-offset voltage, rail-to-rail input and output precision amplifiers, each with a CMOS input stage and a wide supply voltage range. The LMP770x are part of the LMP™ precision amplifier family and are ideal for interface and other instrumentation applications.

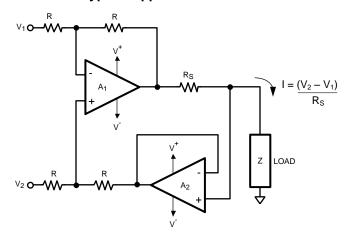
The specified low-offset voltage of less than ±200 µV, along with the specified low input bias current of less than ±1 pA, make the LMP7701 ideal for precision applications. The LMP770x are built using VIP50 technology, which allows the combination of a CMOS input stage and a 12-V common-mode and supply voltage range. This makes the LMP770x ideal for applications where conventional CMOS parts cannot operate under the desired voltage conditions.

#### Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)					
LMD7704	SOT-23 (5)	1.60 mm × 2.90 mm					
LMP7701	SOIC (8)	3.91 mm × 4.90 mm					
LMDZZOO	VSSOP (8)	3.00 mm × 3.00 mm					
LMP7702	SOIC (8)	3.91 mm × 4.90 mm					
LMP7704	TSSOP (14)	4.40 mm × 5.00 mm					
LIVIP / / U4	SOIC (14)	3.91 mm × 8.65 mm					

(1) For all available packages, see the orderable addendum at the end of the data sheet.

#### Typical Application Schematic





## **Table of Contents**

	Factoria		0.0 Functional Block Diagram	2.
1	Features 1		8.2 Functional Block Diagram	
2	Applications 1		8.3 Feature Description	
3	Description 1		8.4 Device Functional Modes	25
4	Revision History2	9	Application and Implementation	25
5	Description (continued)3		9.1 Application Information	25
6	Pin Configuration and Functions		9.2 Typical Application	27
7	Specifications5	10	Power Supply Recommendations	30
•		11	Layout	31
	7.1 Absolute Maximum Ratings		11.1 Layout Guidelines	
	7.3 Recommended Operating Conditions		11.2 Layout Example	31
	7.4 Thermal Information	12	Device and Documentation Support	32
	7.5 Electrical Characteristics 3-V		12.1 Related Links	32
	7.6 Electrical Characteristics 5-V		12.2 Community Resources	32
	7.7 Electrical Characteristics ±5-V		12.3 Trademarks	32
	7.8 Typical Characteristics		12.4 Electrostatic Discharge Caution	32
8	Detailed Description		12.5 Glossary	32
•	8.1 Overview	13	Mechanical, Packaging, and Orderable Information	32

## 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

#### Changes from Revision H (March 2013) to Revision I

**Page** 

Added ESD Ratings table, Feature Description section, Device Functional Modes, Application and Implementation section, Power Supply Recommendations section, Layout section, Device and Documentation Support section, and Mechanical, Packaging, and Orderable Information section.

## Changes from Revision G (March 2013) to Revision H

Page

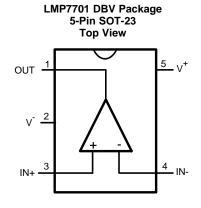


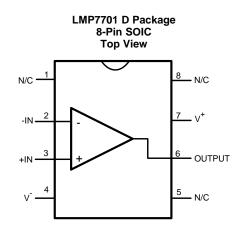
## 5 Description (continued)

The LMP770x each have a rail-to-rail input stage that significantly reduces the CMRR glitch commonly associated with rail-to-rail input amplifiers. This is achieved by trimming both sides of the complimentary input stage, thereby reducing the difference between the NMOS and PMOS offsets. The output of the LMP770x swings within 40 mV of either rail to maximize the signal dynamic range in applications requiring low supply voltage.

The LMP7701 is offered in the space-saving 5-Pin SOT-23 and 8-Pin SOIC package. The LMP7702 is offered in the 8-Pin SOIC and 8-Pin VSSOP package. The quad LMP7704 is offered in the 14-Pin SOIC and 14-Pin TSSOP package. These small packages are ideal solutions for area constrained PC boards and portable electronics.

## 6 Pin Configuration and Functions





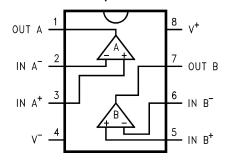
Pin Functions - LMP7701

PIN		1/0	DESCRIPTION				
NAME	SOT-23	SOIC	1/0	DESCRIPTION			
IN+	3	3	I	Noninverting Input			
IN-	4	2	I	Inverting Input			
IN A +	_	_	I	Noninverting Input for Amplifier A			
IN A <sup>-</sup>	_	_	I	Inverting Input for Amplifier A			
IN B <sup>+</sup>	_	_	I	Noninverting Input for Amplifier B			
IN B <sup>-</sup>	_	_	I	Inverting Input for Amplifier B			
IN C <sup>+</sup>	_	_	I	Noninverting Input for Amplifier C			
IN C <sup>-</sup>	_	_	I	Inverting Input for Amplifier C			
IN D <sup>+</sup>	_	_	I	Noninverting Input for Amplifier D			
IN D <sup>-</sup>	_	_	I	Inverting Input for Amplifier D			
NC	_	1, 5, 8	_	No connection			
OUT	1	6	0	Output			
OUT A	_	_	0	Output for Amplifier A			
OUT B	_	_	0	Output for Amplifier B			
OUT C	_	_	0	Output for Amplifier C			
OUT D	_	_	0	Output for Amplifier D			
V <sup>+</sup>	5	7	Р	Positive Supply			
V <sup>-</sup>	2	4	Р	Negative Supply			

Copyright © 2005–2015, Texas Instruments Incorporated



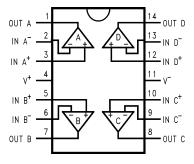
#### LMP7702 D or DGK Package 8-Pin SOIC or VSSOP Top View



#### **Pin Functions - LMP7702**

PIN		1/0	DECORPTION
NAME	SOIC, VSSOP	I/O	DESCRIPTION
IN+	_	I	Noninverting Input
IN-	_	I	Inverting Input
IN A <sup>+</sup>	3	I	Noninverting Input for Amplifier A
IN A <sup>-</sup>	2	I	Inverting Input for Amplifier A
IN B <sup>+</sup>	5	I	Noninverting Input for Amplifier B
IN B <sup>-</sup>	6	I	Inverting Input for Amplifier B
IN C <sup>+</sup>	_	I	Noninverting Input for Amplifier C
IN C <sup>-</sup>	_	I	Inverting Input for Amplifier C
IN D <sup>+</sup>	_	I	Noninverting Input for Amplifier D
IN D <sup>-</sup>	_	I	Inverting Input for Amplifier D
NC	_	_	No connection
OUT	_	0	Output
OUT A	1	0	Output for Amplifier A
OUT B	7	0	Output for Amplifier B
OUT C	_	0	Output for Amplifier C
OUT D	_	0	Output for Amplifier D
V <sup>+</sup>	8	Р	Positive Supply
V <sup>-</sup>	4	Р	Negative Supply

#### LMP7704 D or PW Package 14-Pin SOIC or TSSOP Top View



Submit Documentation Feedback



#### Pin Functions - LMP7704

PIN		1/0	DECODINE IOU
NAME	SOIC, TSSOP	1/0	DESCRIPTION
IN+	_	I	Noninverting Input
IN-	_	I	Inverting Input
IN A <sup>+</sup>	3	1	Noninverting Input for Amplifier A
IN A <sup>-</sup>	2	1	Inverting Input for Amplifier A
IN B <sup>+</sup>	5	I	Noninverting Input for Amplifier B
IN B <sup>-</sup>	6	I	Inverting Input for Amplifier B
IN C <sup>+</sup>	10	I	Noninverting Input for Amplifier C
IN C	9	I	Inverting Input for Amplifier C
IN D <sup>+</sup>	12	1	Noninverting Input for Amplifier D
IN D-	13	I	Inverting Input for Amplifier D
NC	_	_	No connection
OUT	_	0	Output
OUT A	1	0	Output for Amplifier A
OUT B	7	0	Output for Amplifier B
OUT C	8	0	Output for Amplifier C
OUT D	14	0	Output for Amplifier D
V <sup>+</sup>	4	Р	Positive Supply
V <sup>-</sup>	11	Р	Negative Supply

# 7 Specifications

## 7.1 Absolute Maximum Ratings

See (1)(2)

		MIN	MAX	UNIT
V <sub>IN</sub> differential			±300	mV
Supply voltage (V <sub>S</sub> = V <sup>+</sup>	− V <sup>−</sup> )		13.2	V
Voltage at input/output pins			V++ 0.3, V 0.3	
Input current			10	mA
Junction temperature (3)	Junction temperature (3)		+150	
Caldavia a information	Infrared or convection (20 sec)		235	°C
Soldering information	Wave soldering lead temp. (10 sec)		260	°C
Storage temperature, T <sub>stg</sub>		-65	150	°C

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## 7.2 ESD Ratings

			VALUE	UNIT
V <sub>(ESD)</sub> Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)(2)</sup>	±2000		
	discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(3)</sup>	±1000	V
		Machine Model (MM)	±200	

<sup>1)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

<sup>(2)</sup> If Military/Aerospace specified devices are required, contact the TI Sales Office/ Distributors for availability and specifications.

<sup>(3)</sup> The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A)/\theta_{JA}$ . All numbers apply for packages soldered directly onto a PC Board.

<sup>(2)</sup> Human Body Model, applicable std. MIL-STD-883, Method 3015.7. Machine Model, applicable std. JESD22-A115-A (ESD MM std. of JEDEC) Field-Induced Charge-Device Model, applicable std. JESD22-C101-C (ESD FICDM std. of JEDEC).

<sup>(3)</sup> JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



## 7.3 Recommended Operating Conditions

	MIN	NOM MA	X UNIT
Temperature range <sup>(1)</sup>	-40	12	5 °C
Supply voltage $(V_S = V^+ - V^-)$	2.7		2 V

(1) The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A)/\theta_{JA}$ . All numbers apply for packages soldered directly onto a PC Board.

#### 7.4 Thermal Information

		LMP7701 LMP7701, LMP7702 L		LMP7702	LMP		
	THERMAL METRIC <sup>(1)</sup>	DBV (SOT-23)	D (SOIC)	DGK (VSSOP)	D (SOIC)	PW (TSSOP)	UNIT
		5 PINS	8 PINS	8 PINS	14 PINS	14 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance (2)	122.9	114.3	167.5	79.9	107.5	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	69.3	59.5	58.7	36.9	33.0	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	63.3	54.8	87.5	34.7	50.4	°C/W
ΨЈТ	Junction-to-top characterization parameter	19.4	12.1	6.6	5.5	1.8	°C/W
ΨЈВ	Junction-to-board characterization parameter	62.8	54.2	86.1	34.4	49.7	°C/W

For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report (SPRA953).

#### 7.5 Electrical Characteristics 3-V

Unless otherwise specified, all limits are ensured for  $T_A$  = 25°C,  $V^+$  = 3 V,  $V^-$  = 0 V,  $V_{CM}$  =  $V^+/2$ , and  $R_L$  > 10 k $\Omega$  to  $V^+/2$ . (1)

PARAMETER		TEST COM	NDITIONS	MIN <sup>(2)</sup>	TYP (3)	MAX <sup>(2)</sup>	UNIT
					±37	±200	
	Innut Officet Voltage	LMP7701	at the temperature extremes			±500	/
Vos	Input Offset Voltage				±56	±220	μV
		LMP7702/LMP7704	at the temperature extremes			±520	1
	TCV <sub>OS</sub> Input Offset Voltage Temperature Drift				±1		
TCV <sub>OS</sub>		See (4)	at the temperature extremes			±5	μV/°C
		See (4) (5)			±0.2	±1	
	Innut Rica Current	-40°C ≤ T <sub>A</sub> ≤ 85°C	at the temperature extremes			±50	<b>~</b> ^
I <sub>B</sub>	Input Bias Current	See (4) (5)			±0.2	±1	pА
		-40°C ≤ T <sub>A</sub> ≤ 125°C	at the temperature extremes			±400	İ
Ios	Input Offset Current		<u> </u>		40		fA

Submit Documentation Feedback

<sup>(2)</sup> The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A)/\theta_{JA}$ . All numbers apply for packages soldered directly onto a PC Board.

<sup>(1)</sup> Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that T<sub>J</sub> = T<sub>A</sub>. No specification of parametric performance is indicated in the electrical tables under conditions of internal self-heating where T<sub>J</sub> > T<sub>A</sub>.

<sup>(2)</sup> Limits are 100% production tested at 25°C. Limits over the operating temperature range are specified through correlations using the Statistical Quality Control (SQC) method.

<sup>(3)</sup> Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not specified on shipped production material.

<sup>4)</sup> This parameter is specified by design and/or characterization and is not tested in production.

<sup>(5)</sup> Positive current corresponds to current flowing into the device.



# **Electrical Characteristics 3-V (continued)**

Unless otherwise specified, all limits are ensured for  $T_A = 25^{\circ}C$ ,  $V^+ = 3$  V,  $V^- = 0$  V,  $V_{CM} = V^+/2$ , and  $R_L > 10$  k $\Omega$  to  $V^+/2$ . (1)

	PARAMETER	TEST CONI	DITIONS	MIN <sup>(2)</sup>	TYP (3)	MAX (2)	UNIT
		0 V ≤ V <sub>CM</sub> ≤ 3 V		86	130		
CMDD		LMP7701	at the temperature extremes	80			ЧD
CMRR	Common-Mode Rejection Ratio	0.1/2.1/		84	130		dB
		0 V ≤ V <sub>CM</sub> ≤ 3 V LMP7702/LMP7704	at the temperature extremes	78			
				86	98		
PSRR	Power Supply Rejection Ratio	$2.7 \text{ V} \le \text{V}^+ \le 12 \text{ V}, \text{ Vo} = \text{V}^+/2$	at the temperature extremes	82			dB
		CMRR ≥ 80 dB		-0.2		3.2	
CMVR	Common-Mode Voltage Range	CMRR ≥ 77 dB	at the temperature extremes	-0.2		3.2	V
		P = 2 kO (LMD7701)		100	114		
		$R_L = 2 k\Omega \text{ (LMP7701)}$ $V_O = 0.3 \text{ V to } 2.7 \text{ V}$	at the temperature extremes	96			
		$R_L = 2 k\Omega$		100	114		
A <sub>VOL</sub>	Open-Loop Voltage Gain	(LMP7702/LMP7704) V <sub>O</sub> = 0.3 V to 2.7 V	at the temperature extremes	94			dB
		$R_L = 10 \text{ k}\Omega$ $V_O = 0.2 \text{ V to } 2.8 \text{ V}$		100	124		
			at the temperature extremes	96			
V <sub>OUT</sub>		$R_L = 2 k\Omega \text{ to V}^{+}/2$ LMP7701			40	80	
			at the temperature extremes			120	
		P 2 kO to \/†/2			40	80	
	Output Voltage Swing High	$R_L = 2 \text{ k}\Omega \text{ to V}^+/2$ LMP7702/LMP7704	at the temperature extremes			150	mV
	Output voltage Swing Flight	$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$			30	40	
		LMP7701	at the temperature extremes			60	
		$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$			35	50	
		LMP7702/LMP7704	at the temperature extremes			100	
		$R_L = 2 k\Omega$ to V <sup>+</sup> /2			40	60	
		LMP7701	at the temperature extremes			80	
		$R_L = 2 k\Omega$ to $V^+/2$			45	100	
	Output Voltage Swing Low	LMP7702/LMP7704	at the temperature extremes			170	mV
	Salpat voltage Swilly Low	$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$			20	40	111 V
		LMP7701	at the temperature extremes			50	
		$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$			20	50	
		LMP7702/LMP7704	at the temperature extremes			90	

Copyright © 2005–2015, Texas Instruments Incorporated



## **Electrical Characteristics 3-V (continued)**

Unless otherwise specified, all limits are ensured for  $T_A$  = 25°C,  $V^+$  = 3 V,  $V^-$  = 0 V,  $V_{CM}$  =  $V^+/2$ , and  $R_L$  > 10 k $\Omega$  to  $V^+/2$ . (1)

	PARAMETER	TEST CON	DITIONS	MIN <sup>(2)</sup>	TYP (3)	MAX <sup>(2)</sup>	UNIT
		Coursing V V+/2		25	42		
		Sourcing $V_O = V^+/2$ $V_{IN} = 100 \text{ mV}$	at the temperature extremes	15			
		Cipling \/ \/t/0		25	42		
I <sub>OUT</sub>	Output Current (6) (7)	Sinking $V_O = V^+/2$ $V_{IN} = -100 \text{ mV (LMP7701)}$	at the temperature extremes	20			mA
		Sinking V <sub>O</sub> = V <sup>+</sup> /2		25	42		
		V <sub>IN</sub> = −100 mV (LMP7702/LMP7704)	at the temperature extremes	15			
	Supply Current				0.670	1	
		LMP7701	at the temperature extremes			1.2	mA
		LMP7702			1.4	1.8	
Is			at the temperature extremes			2.1	
					2.9	3.5	
		LMP7704	at the temperature extremes			4.5	
SR	Slew Rate <sup>(8)</sup>	A <sub>V</sub> = +1, V <sub>O</sub> = 2 V <sub>PP</sub> 10% to 90%			0.9		V/µs
GBW	Gain Bandwidth				2.5		MHz
THD+N	Total Harmonic Distortion + Noise	$f=1~kHz,~A_V=1,~RL=10~k\Omega$			0.02%		
e <sub>n</sub>	Input Referred Voltage Noise Density	f = 1 kHz			9		nV/√ <del>Hz</del>
i <sub>n</sub>	Input Referred Current Noise Density	f = 100 kHz			1		fA/√Hz

The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A)/\theta_{JA}$ . All numbers apply for packages soldered directly onto a PC Board. The short circuit test is a momentary test.

Submit Documentation Feedback

<sup>(8)</sup> The number specified is the slower of positive and negative slew rates.



#### 7.6 Electrical Characteristics 5-V

Unless otherwise specified, all limits are ensured for  $T_A = 25^{\circ}C$ ,  $V^+ = 5$  V,  $V^- = 0$  V,  $V_{CM} = V^+/2$ , and  $R_L > 10$  k $\Omega$  to  $V^+/2$ . (1)

PARAMETER		TEST CONI	MIN <sup>(2)</sup>	TYP (3)	MAX (2)	UNIT		
					±37	±200		
V	Input Offset Voltage	LMP7701	at the temperature extremes			±500	μV	
V <sub>OS</sub>	input Onset voltage				±32	±220	μν	
		LMP7702/LMP7704	at the temperature extremes			±520		
	land Offeet Veltage				±1	±5		
TCV <sub>OS</sub>	Input Offset Voltage Temperature Drift	See <sup>(4)</sup>	at the temperature extremes				μV/°C	
		See (4) (5)			±0.2	±1		
	January Dies Comment	-40°C ≤ T <sub>A</sub> ≤ 85°C	at the temperature extremes			±50	A	
I <sub>B</sub> In	Input Bias Current	See (4) (5)			±0.2	±1	pA	
		-40°C ≤ T <sub>A</sub> ≤ 125°C	at the temperature extremes			±400		
Ios	Input Offset Current				40		fA	
	Common-Mode Rejection Ratio	0 V ≤ V <sub>CM</sub> ≤ 5 V		88	130			
CMDD		LMP7701	at the temperature extremes	83			٩D	
CMRR		0 \ < \ \ < 5 \ \		86	130		dB	
		0 V ≤ V <sub>CM</sub> ≤ 5 V LMP7702/LMP7704	at the temperature extremes	81				
				86	100		dB	
PSRR	Power Supply Rejection Ratio	$2.7 \text{ V} \le \text{V}^+ \le 12 \text{ V}, \text{ V}_0 = \text{V}^+/2$	at the temperature extremes	82				
		CMRR ≥ 80 dB		-0.2		5.2		
CMVR	Common-Mode Voltage Range	CMRR ≥ 78 dB	at the temperature extremes	-0.2		5.2	V	
		D 0 100 (LMD7704)		100	119			
		$R_L = 2 k\Omega \text{ (LMP7701)}$ $V_O = 0.3 \text{ V to } 4.7 \text{ V}$	at the temperature extremes	96				
		$R_L = 2 k\Omega$		100	119		dB	
A <sub>VOL</sub>	Open-Loop Voltage Gain	(LMP7702/LMP7704) V <sub>O</sub> = 0.3 V to 4.7 V	at the temperature extremes	94				
		$R_{L} = 10 \text{ k}\Omega$		100	130			
		$V_0 = 0.2 \text{ V to } 4.8 \text{ V}$	at the temperature extremes	96				

<sup>(1)</sup> Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that T<sub>J</sub> = T<sub>A</sub>. No specification of parametric performance is indicated in the electrical tables under conditions of internal self-heating where T<sub>J</sub> > T<sub>A</sub>.

<sup>(2)</sup> Limits are 100% production tested at 25°C. Limits over the operating temperature range are specified through correlations using the Statistical Quality Control (SQC) method.

<sup>(3)</sup> Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.

<sup>(4)</sup> This parameter is specified by design and/or characterization and is not tested in production.

<sup>(5)</sup> Positive current corresponds to current flowing into the device.



## **Electrical Characteristics 5-V (continued)**

Unless otherwise specified, all limits are ensured for  $T_A = 25^{\circ}C$ ,  $V^+ = 5$  V,  $V^- = 0$  V,  $V_{CM} = V^+/2$ , and  $R_1 > 10$  k $\Omega$  to  $V^+/2$ .

	PARAMETER	TEST CON	TEST CONDITIONS					
		$R_L = 2 k\Omega \text{ to } V^+/2$ LMP7701	at the temperature extremes		60	110 130		
		$R_L = 2 k\Omega \text{ to } V^+/2$			60	120		
	Output Voltage Swing High	LMP7702/LMP7704	at the temperature extremes			200	mV from V <sup>+</sup>	
		$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$ LMP7701	at the temperature extremes		40	50 70	IIOIII V	
			extremes		40	60		
.,		$R_L = 10 \text{ k}\Omega \text{ to V}^+/2 $ LMP7702/LMP7704	at the temperature extremes			120		
V <sub>OUT</sub>		$R_L = 2 k\Omega \text{ to } V^+/2$			50	80		
	Output Voltage Swing Low	LMP7701	at the temperature extremes			90		
		$R_1 = 2 k\Omega$ to $V^+/2$			50	120		
		LMP7702/LMP7704	at the temperature extremes			190	mV	
		$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$ LMP7701	at the temperature		30	50 50		
			extremes		30	50		
		$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$ LMP7702/LMP7704	at the temperature extremes			100		
		Sourcing \/ \/ <sup>+</sup> /2	Sourcing V <sub>O</sub> = V <sup>+</sup> /2		66			
		V <sub>IN</sub> = 100 mV (LMP7701)	at the temperature extremes	28				
		Sourcing $V_0 = V^+/2$		38	66			
I <sub>OUT</sub>	Output Current (6) (7)	V <sub>IN</sub> = 100 mV (LMP7702/LMP7704)	at the temperature extremes	25			mA	
-001		Sinking $V_O = V^+/2$		40	76			
		V <sub>IN</sub> = -100 mV (LMP7701)	at the temperature extremes	28				
		Sinking $V_O = V^+/2$ $V_{IN} = -100 \text{ mV}$	at the temperature	23	76			
		(LMP7702/LMP7704)	extremes	23	0.745			
		LMP7701	at the temperature extremes		0.715	1.2		
			SAI OTTIOO		1.5	1.9		
I <sub>S</sub>	Supply Current	LMP7702	at the temperature extremes			2.2	mA	
					2.9	3.7		
		LMP7704	at the temperature extremes			4.6		
SR	Slew Rate (8)	$A_V = +1, V_O = 4 V_{PP}$ 10% to 90%			1		V/µs	
GBW	Gain Bandwidth				2.5		MHz	

<sup>(6)</sup> The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A)/\theta_{JA}$ . All numbers apply for packages soldered directly onto a PC Board.

Submit Documentation Feedback

The short circuit test is a momentary test.

The number specified is the slower of positive and negative slew rates. (8)



## **Electrical Characteristics 5-V (continued)**

Unless otherwise specified, all limits are ensured for  $T_A$  = 25°C,  $V^+$  = 5 V,  $V^-$  = 0 V,  $V_{CM}$  =  $V^+/2$ , and  $R_L$  > 10 k $\Omega$  to  $V^+/2$ . (1)

	PARAMETER	TEST CONDITIONS	MIN (2) TYP (3) MAX (2)	UNIT
THD+N	Total Harmonic Distortion + Noise	$f = 1 \text{ kHz}, A_V = 1, R_L = 10 \text{ k}\Omega$	0.02%	
e <sub>n</sub>	Input Referred Voltage Noise Density	f = 1 kHz	9	nV/√ <del>Hz</del>
i <sub>n</sub>	Input Referred Current Noise Density	f = 100 kHz	1	fA/√Hz

#### 7.7 Electrical Characteristics ±5-V

Unless otherwise specified, all limits are ensured for  $T_A = 25$ °C,  $V^+ = 5$  V,  $V^- = -5$  V,  $V_{CM} = 0$  V, and  $R_L > 10$  k $\Omega$  to 0 V. (1)

	PARAMETER	TEST CONDITIONS			TYP (3)	MAX (2)	UNIT	
					±37	±200		
V	Input Officet Voltage	LMP7701	at the temperature extremes			±500	/	
Vos	Input Offset Voltage				±37	±220	μV	
		LMP7702/LMP7704	at the temperature extremes			±520		
	land Officet Valtage				±1			
TCV <sub>OS</sub>	Input Offset Voltage Temperature Drift	See (4)	at the temperature extremes			±5	μV/°C	
		See (4) (5)			±0.2	1		
	Input Bias Current	-40°C ≤ T <sub>A</sub> ≤ 85°C	at the temperature extremes			±50	<b>~</b> ^	
I <sub>B</sub>		See (4) (5)			±0.2	1	pА	
		-40°C ≤ T <sub>A</sub> ≤ 125°C	at the temperature extremes			±400		
Ios	Input Offset Current				40		fA	
				92	138			
CMDD	Common Mada Paination Patin	-5 V ≤ V <sub>CM</sub> ≤ 5 V LMP7701	at the temperature extremes	88			ا	
CMRR	Common-Mode Rejection Ratio	5.V.2.V. 2.5.V.		90	138		dB	
		-5 V ≤ V <sub>CM</sub> ≤ 5 V LMP7702/LMP7704	at the temperature extremes	86				
				86	98			
PSRR	Power Supply Rejection Ratio	$2.7 \text{ V} \le \text{V}^+ \le 12 \text{ V}, \text{ V}_0 = 0 \text{ V}$	at the temperature extremes	82			dB	
		CMRR ≥ 80 dB		-5.2		5.2		
CMVR	Common-Mode Voltage Range	CMRR ≥ 78 dB	at the temperature extremes	-5.2		5.2	V	

<sup>(1)</sup> Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that T<sub>J</sub> = T<sub>A</sub>. No specification of parametric performance is indicated in the electrical tables under conditions of internal self-heating where T<sub>J</sub> > T<sub>A</sub>.

<sup>(2)</sup> Limits are 100% production tested at 25°C. Limits over the operating temperature range are specified through correlations using the Statistical Quality Control (SQC) method.

<sup>(3)</sup> Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.

<sup>(4)</sup> This parameter is specified by design and/or characterization and is not tested in production.

<sup>(5)</sup> Positive current corresponds to current flowing into the device.



## **Electrical Characteristics ±5-V (continued)**

Unless otherwise specified, all limits are ensured for  $T_A = 25^{\circ}C$ ,  $V^+ = 5$  V,  $V^- = -5$  V,  $V_{CM} = 0$  V, and  $R_1 > 10$  k $\Omega$  to 0 V.<sup>(1)</sup>

PARAMETER		are ensured for $T_A = 25^{\circ}C$ , V		TYP (3)		UNIT		
		B 010 (1117-701)		100	121			
		$R_L = 2 k\Omega \text{ (LMP7701)}$ $V_O = -4.7 \text{ V to } 4.7 \text{ V}$	at the temperature extremes	98				
		$R_L = 2 k\Omega$		100	121			
A <sub>VOL</sub>	Open Loop Voltage Gain	(LMP7702/LMP7704) $V_0 = -4.7 \text{ V to } 4.7 \text{ V}$	at the temperature extremes	94			dB	
AVOL		$R_L = 10 \text{ k}\Omega \text{ (LMP7701)}$		100	134		uБ	
		$V_O = -4.8 \text{ V to } 4.8 \text{ V}$	at the temperature extremes	98				
		$R_L = 10 \text{ k}\Omega$		100	134			
		(LMP7702/LMP7704) $V_O = -4.8 \text{ V to } 4.8 \text{ V}$	at the temperature extremes	97				
		$R_L = 2 k\Omega$ to 0 V			90	150		
		LMP7701	at the temperature extremes			170		
	Output Voltage Swing High	$R_L = 2 k\Omega$ to 0 V			90	180		
		LMP7702/LMP7704	at the temperature extremes			290	mV from V <sup>+</sup>	
		$R_1 = 10 \text{ k}\Omega \text{ to } 0 \text{ V}$			40	80		
		LMP7701	at the temperature extremes			100		
		D 40 k0 to 0 V			40	80		
\/		$R_L = 10 \text{ k}\Omega \text{ to } 0 \text{ V}$ LMP7702/LMP7704	at the temperature extremes			150		
V <sub>OUT</sub>		$R_L = 2 k\Omega$ to 0 V			90	130		
		LMP7701	at the temperature extremes			150		
		B = 2 kO to 0 V			90	180		
	Output Valtage Swing Low	$R_L = 2 k\Omega$ to 0 V LMP7702/LMP7704	at the temperature extremes			260		
	Output Voltage Swing Low	$R_{I} = 10 \text{ k}\Omega \text{ to } 0 \text{ V}$			40	50	from V <sup>-</sup>	
		LMP7701	at the temperature extremes			60		
		$R_1 = 10 \text{ k}\Omega \text{ to } 0 \text{ V}$			40	60		
		LMP7702/LMP7704	at the temperature extremes			110		
		Sourcing V <sub>O</sub> = 0 V		50	86			
		V <sub>IN</sub> = 100 mV (LMP7701)	at the temperature extremes	35				
	- (0) (7)	Sourcing V <sub>O</sub> = 0 V		48	86		mA	
I <sub>OUT</sub>	Output Current (6) (7)	V <sub>IN</sub> = 100 mV (LMP7702/LMP7704)	at the temperature extremes	33				
		Sinking V <sub>O</sub> = 0 V		50	84			
		$V_{IN} = -100 \text{ mV}$	at the temperature extremes	35				

Submit Documentation Feedback

 <sup>(6)</sup> The maximum power dissipation is a function of T<sub>J(MAX)</sub>, θ<sub>JA</sub>. The maximum allowable power dissipation at any ambient temperature is P<sub>D</sub> = (T<sub>J(MAX)</sub> - T<sub>A</sub>)/ θ<sub>JA</sub>. All numbers apply for packages soldered directly onto a PC Board.
 (7) The short circuit test is a momentary test.



## **Electrical Characteristics ±5-V (continued)**

Unless otherwise specified, all limits are ensured for  $T_A = 25$ °C,  $V^+ = 5$  V,  $V^- = -5$  V,  $V_{CM} = 0$  V, and  $R_L > 10$  k $\Omega$  to 0 V. (1)

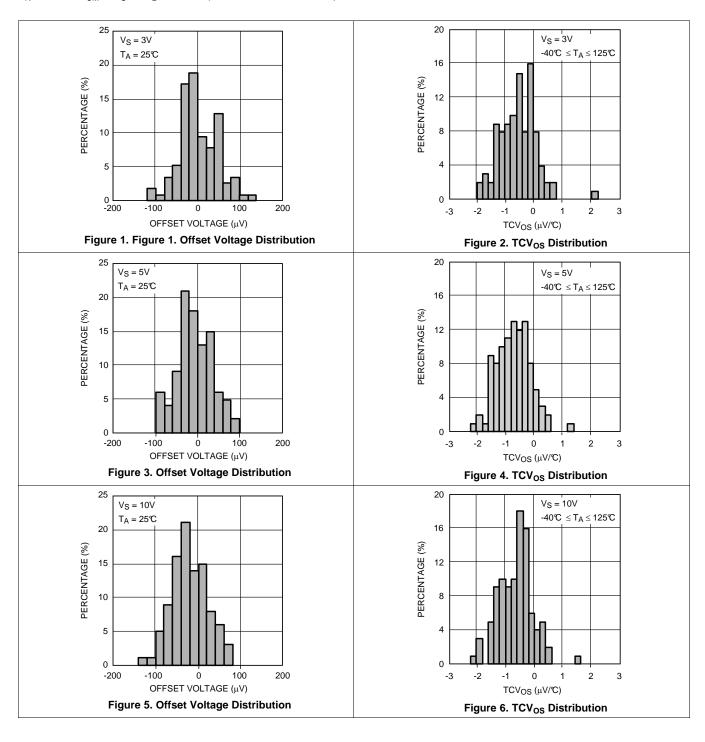
PARAMETER		TEST CON	DITIONS	MIN <sup>(2)</sup>	TYP (3)	MAX <sup>(2)</sup>	UNIT
					0.790	1.1	
		LMP7701	at the temperature extremes			1.3	
					1.7	2.1	
I <sub>S</sub>	Supply Current	LMP7702	at the temperature extremes			2.5	mA
					3.2	4.2	
		LMP7704	at the temperature extremes			5	
SR	Slew Rate <sup>(8)</sup>	$A_V = +1$ , $V_O = 9 V_{PP}$ 10% to 90%			1.1		V/µs
GBW	Gain Bandwidth				2.5		MHz
THD+N	Total Harmonic Distortion + Noise	$f = 1 \text{ kHz}, A_V = 1, R_L = 10 \text{ k}\Omega$			0.02%		
e <sub>n</sub>	Input Referred Voltage Noise Density	f = 1 kHz			9		nV/√ <del>Hz</del>
i <sub>n</sub>	Input Referred Current Noise Density	f = 100 kHz		1		fA/√Hz	

<sup>(8)</sup> The number specified is the slower of positive and negative slew rates.



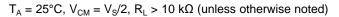
## 7.8 Typical Characteristics

 $T_A$  = 25°C,  $V_{CM}$  =  $V_S/2$ ,  $R_L$  > 10 k $\Omega$  (unless otherwise noted)



Submit Documentation Feedback





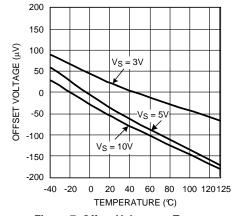


Figure 7. Offset Voltage vs Temperature

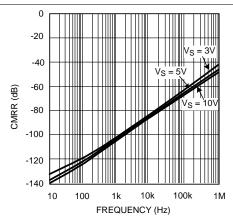


Figure 8. CMRR vs Frequency

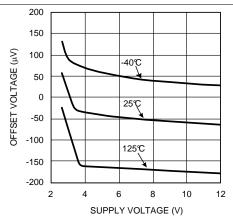


Figure 9. Offset Voltage vs Supply Voltage

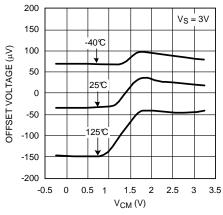


Figure 10. Offset Voltage vs V<sub>CM</sub>

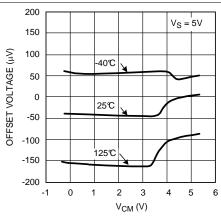


Figure 11. Offset Voltage vs V<sub>CM</sub>

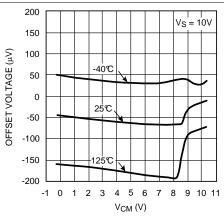
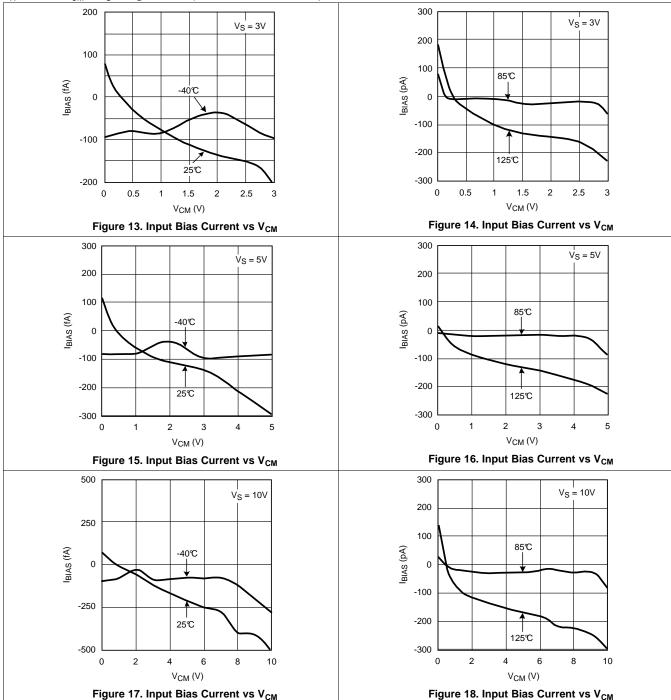


Figure 12. Offset Voltage vs V<sub>CM</sub>



 $T_A$  = 25°C,  $V_{CM}$  =  $V_S/2$ ,  $R_L$  > 10 k $\Omega$  (unless otherwise noted)





 $T_A$  = 25°C,  $V_{CM}$  =  $V_S/2$ ,  $R_L$  > 10 k $\Omega$  (unless otherwise noted)

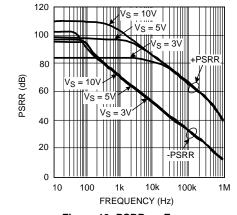


Figure 19. PSRR vs Frequency

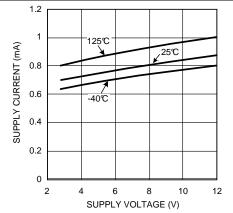


Figure 20. Supply Current vs Supply Voltage (Per Channel)

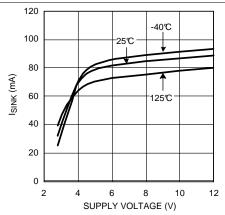


Figure 21. Sinking Current vs Supply Voltage

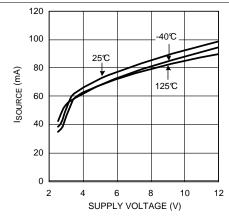


Figure 22. Sourcing Current vs Supply Voltage

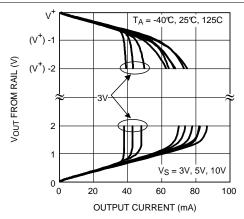


Figure 23. Output Voltage vs Output Current

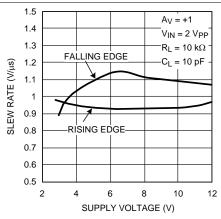
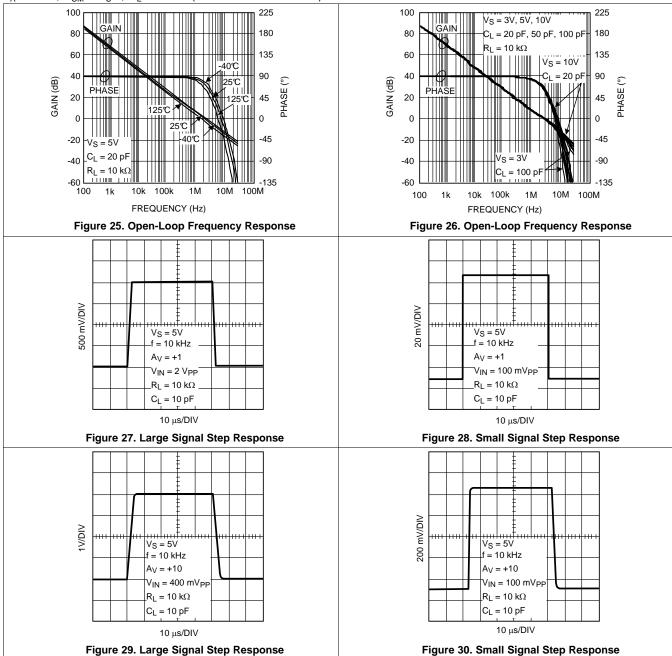


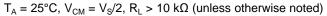
Figure 24. Slew Rate vs Supply Voltage



 $T_A = 25$ °C,  $V_{CM} = V_S/2$ ,  $R_L > 10 \text{ k}\Omega$  (unless otherwise noted)







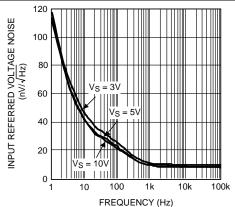


Figure 31. Input Voltage Noise vs Frequency

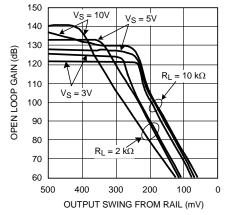


Figure 32. Open Loop Gain vs Output Voltage Swing

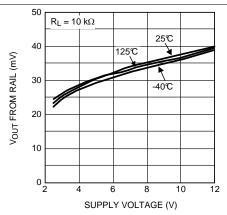


Figure 33. Output Swing High vs Supply Voltage

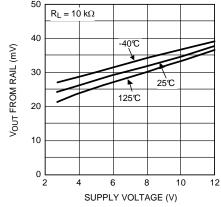


Figure 34. Output Swing Low vs Supply Voltage

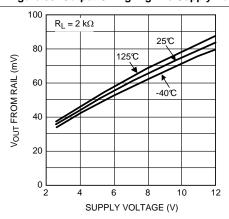


Figure 35. Output Swing High vs Supply Voltage

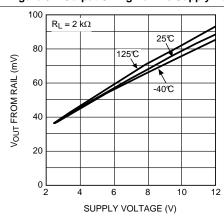
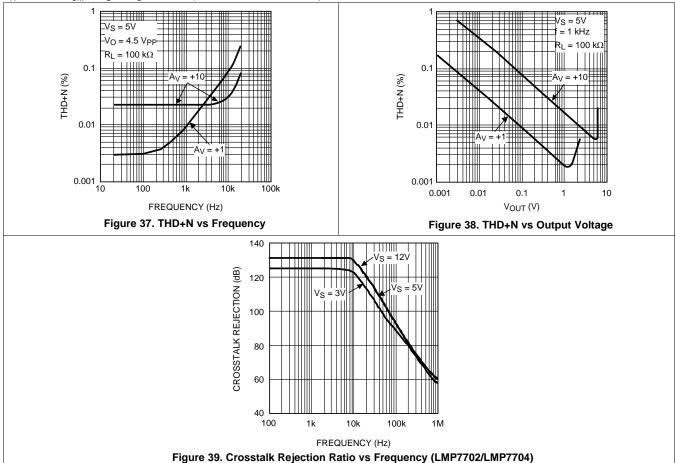


Figure 36. Output Swing Low vs Supply Voltage



 $T_A = 25$ °C,  $V_{CM} = V_S/2$ ,  $R_L > 10 \text{ k}\Omega$  (unless otherwise noted)





## 8 Detailed Description

#### 8.1 Overview

The LMP770x are single, dual, and quad low offset voltage, rail-to-rail input and output precision amplifiers each with a CMOS input stage and wide supply voltage range of 2.7V to 12V. The LMP770x have a very low input bias current of only ±200 fA at room temperature.

The wide supply voltage range of 2.7V to 12V over the extensive temperature range of -40°C to 125°C makes the LMP770x excellent choices for low voltage precision applications with extensive temperature requirements.

The LMP770x have only  $\pm 37~\mu V$  of typical input referred offset voltage and this offset is specified to be less than  $\pm 500~\mu V$  for the single and  $\pm 520~\mu V$  for the dual and quad, over temperature. This minimal offset voltage allows more accurate signal detection and amplification in precision applications.

The low input bias current of only  $\pm 200$  fA along with the low input referred voltage noise of 9 nV/ $\sqrt{\text{Hz}}$  gives the LMP770x superiority for use in sensor applications. Lower levels of noise from the LMP770x mean of better signal fidelity and a higher signal-to-noise ratio.

Texas Instruments is heavily committed to precision amplifiers and the market segment they serve. Technical support and extensive characterization data is available for sensitive applications or applications with a constrained error budget.

The LMP7701 is offered in the space saving 5-Pin SOT-23 and 8-Pin SOIC package. The LMP7702 comes in the 8-Pin SOIC and 8-Pin VSSOP package. The LMP7704 is offered in the 14-Pin SOIC and 14-Pin TSSOP package. These small packages are ideal solutions for area constrained PC boards and portable electronics.

## 8.2 Functional Block Diagram

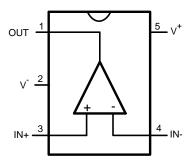


Figure 40. Functional Block Diagram (LMP7701)

#### 8.3 Feature Description

#### 8.3.1 Capacitive Load

The LMP770x can each be connected as a non-inverting unity gain follower. This configuration is the most sensitive to capacitive loading.

The combination of a capacitive load placed on the output of an amplifier along with the amplifier's output impedance creates a phase lag which in turn reduces the phase margin of the amplifier. If the phase margin is significantly reduced, the response will be either underdamped or it will oscillate.

To drive heavier capacitive loads, an isolation resistor,  $R_{\rm ISO}$ , in Figure 41 should be used. By using this isolation resistor, the capacitive load is isolated from the amplifier's output, and hence, the pole caused by  $C_L$  is no longer in the feedback loop. The larger the value of  $R_{\rm ISO}$ , the more stable the output voltage will be. If values of  $R_{\rm ISO}$  are sufficiently large, the feedback loop will be stable, independent of the value of  $C_L$ . However, larger values of  $R_{\rm ISO}$  result in reduced output swing and reduced output current drive.

Copyright © 2005–2015, Texas Instruments Incorporated

## Feature Description (continued)

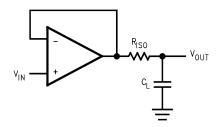


Figure 41. Isolating Capacitive Load

#### 8.3.2 Input Capacitance

CMOS input stages inherently have low input bias current and higher input referred voltage noise. The LMP770x enhance this performance by having the low input bias current of only ±200 fA, as well as, a very low input referred voltage noise of 9 nV/√Hz. To achieve this a larger input stage has been used. This larger input stage increases the input capacitance of the LMP770x. The typical value of this input capacitance, CIN, for the LMP770x is 25 pF. The input capacitance will interact with other impedances such as gain and feedback resistors, which are seen on the inputs of the amplifier, to form a pole. This pole will have little or no effect on the output of the amplifier at low frequencies and DC conditions, but will play a bigger role as the frequency increases. At higher frequencies, the presence of this pole will decrease phase margin and will also cause gain peaking. To compensate for the input capacitance, care must be taken in choosing the feedback resistors. In addition to being selective in picking values for the feedback resistor, a capacitor can be added to the feedback path to increase stability.

The DC gain of the circuit shown in Figure 42 is simply  $-R_2/R_1$ .

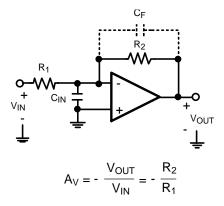


Figure 42. Compensating for Input Capacitance

For the time being, ignore C<sub>F</sub>. The AC gain of the circuit in Figure 42 can be calculated as follows:

$$\frac{V_{\text{OUT}}}{V_{\text{IN}}}(s) = \frac{-R_2/R_1}{\left[1 + \frac{s}{\left(\frac{A_0 R_1}{R_1 + R_2}\right)} + \left(\frac{A_0}{C_{\text{IN}} R_2}\right)\right]}$$
(1)

This equation is rearranged to find the location of the two poles:

$$P_{1,2} = \frac{-1}{2C_{IN}} \left[ \frac{1}{R_1} + \frac{1}{R_2} \pm \sqrt{\left(\frac{1}{R_1} + \frac{1}{R_2}\right)^2 - \frac{4A_0C_{IN}}{R_2}} \right]$$
 (2)



## **Feature Description (continued)**

As shown in Equation 2, as values of  $R_1$  and  $R_2$  are increased, the magnitude of the poles is reduced, which in turn decreases the bandwidth of the amplifier. Whenever possible, it is best to choose smaller feedback resistors. Figure 43 shows the effect of the feedback resistor on the bandwidth of the LMP770x.

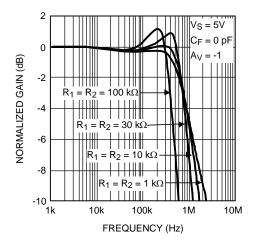


Figure 43. Closed-Loop Gain vs Frequency

Equation 2 has two poles. In most cases, it is the presence of pairs of poles that causes gain peaking. To eliminate this effect, the poles should be placed in Butterworth position, because poles in Butterworth position do not cause gain peaking. To achieve a Butterworth pair, the quantity under the square root in Equation 2 should be set to equal -1. Using this fact and the relation between  $R_1$  and  $R_2$ ,  $R_2 = -A_V R_1$ , the optimum value for  $R_1$  can be found. This is shown in Equation 3. If  $R_1$  is chosen to be larger than this optimum value, gain peaking will occur.

$$R_1 < \frac{(1 - A_V)^2}{2A_0A_VC_{IN}} \tag{3}$$

In Figure 42,  $C_F$  is added to compensate for input capacitance and to increase stability. Additionally,  $C_F$  reduces or eliminates the gain peaking that can be caused by having a larger feedback resistor. Figure 44 shows how  $C_F$  reduces gain peaking.

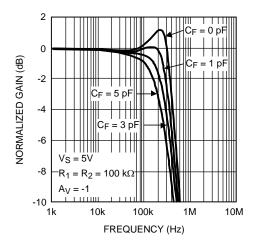


Figure 44. Closed-Loop Gain vs Frequency With Compensation



## **Feature Description (continued)**

#### 8.3.3 Diodes Between the Inputs

The LMP770x have a set of anti-parallel diodes between the input pins, as shown in Figure 45. These diodes are present to protect the input stage of the amplifier. At the same time, they limit the amount of differential input voltage that is allowed on the input pins. A differential signal larger than one diode voltage drop might damage the diodes. The differential signal between the inputs needs to be limited to ±300 mV or the input current needs to be limited to ±10 mA.

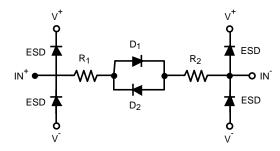


Figure 45. Input of LMP7701



#### 8.4 Device Functional Modes

#### 8.4.1 Precision Current Source

The LMP770x can each be used as a precision current source in many different applications. Figure 46 shows a typical precision current source. This circuit implements a precision voltage controlled current source. Amplifier A1 is a differential amplifier that uses the voltage drop across  $R_{\rm S}$  as the feedback signal. Amplifier A2 is a buffer that eliminates the error current from the load side of the  $R_{\rm S}$  resistor that would flow in the feedback resistor if it were connected to the load side of the  $R_{\rm S}$  resistor. In general, the circuit is stable as long as the closed loop bandwidth of amplifier A2 is greater then the closed loop bandwidth of amplifiers, then the feedback around A1 will reduce its bandwidth compared to A2.

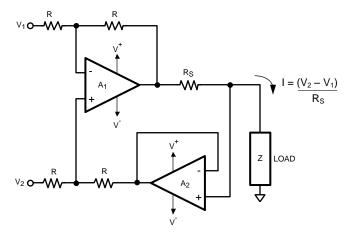


Figure 46. Precision Current Source

The equation for output current can be derived as shown in Equation 4.

$$\frac{V_2R}{R+R} + \frac{(V_0 - IR_S)R}{R+R} = \frac{V_1R}{R+R} + \frac{V_0R}{R+R}$$
(4)

Solving for the current I results in the Equation 5.

$$I = \frac{V_2 - V_1}{R_S} \tag{5}$$

# 9 Application and Implementation

#### **NOTE**

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

## 9.1 Application Information

## 9.1.1 Low Input Voltage Noise

The LMP770x have the very low input voltage noise of  $9 \text{ nV}/\sqrt{\text{Hz}}$ . This input voltage noise can be further reduced by placing N amplifiers in parallel as shown in Figure 47. The total voltage noise on the output of this circuit is divided by the square root of the number of amplifiers used in this parallel combination. This is because each individual amplifier acts as an independent noise source, and the average noise of independent sources is the quadrature sum of the independent sources divided by the number of sources. For N identical amplifiers, this means:

Copyright © 2005–2015, Texas Instruments Incorporated Submit Doct



## **Application Information (continued)**

REDUCED INPUT VOLTAGE NOISE = 
$$\frac{1}{N} \sqrt{e_{n1}^2 + e_{n2}^2 + \dots + e_{nN}^2}$$
  
=  $\frac{1}{N} \sqrt{Ne_n^2} = \frac{\sqrt{N}}{N} e_n$   
=  $\frac{1}{\sqrt{N}} e_n$  (6)

Figure 47 shows a schematic of this input voltage noise reduction circuit. Typical resistor values are:  $R_G = 10\Omega$ ,  $R_F = 1$  k $\Omega$ , and  $R_O = 1$  k $\Omega$ .

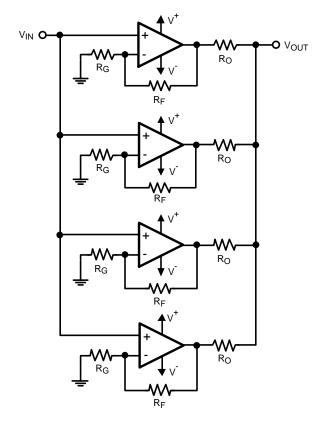


Figure 47. Noise Reduction Circuit

#### 9.1.2 Total Noise Contribution

The LMP770x have very low input bias current, very low input current noise, and very low input voltage noise. As a result, these amplifiers are ideal choices for circuits with high impedance sensor applications.

Figure 48 shows the typical input noise of the LMP770x as a function of source resistance where:

en denotes the input referred voltage noise

 $e_i$  is the voltage drop across source resistance due to input referred current noise or  $e_i = R_S * i_n$ 

et shows the thermal noise of the source resistance

eni shows the total noise on the input.

Where:

$$e_{ni} = \sqrt{e_n^2 + e_i^2 + e_t^2}$$

Submit Documentation Feedback



## **Application Information (continued)**

The input current noise of the LMP770x is so low that it will not become the dominant factor in the total noise unless source resistance exceeds 300  $M\Omega$ , which is an unrealistically high value.

As is evident in Figure 48, at lower  $R_S$  values, total noise is dominated by the amplifier's input voltage noise. Once  $R_S$  is larger than a few kilo-Ohms, then the dominant noise factor becomes the thermal noise of  $R_S$ . As mentioned before, the current noise will not be the dominant noise factor for any practical application.

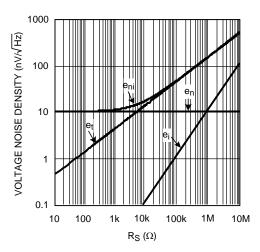


Figure 48. Total Input Noise

## 9.2 Typical Application

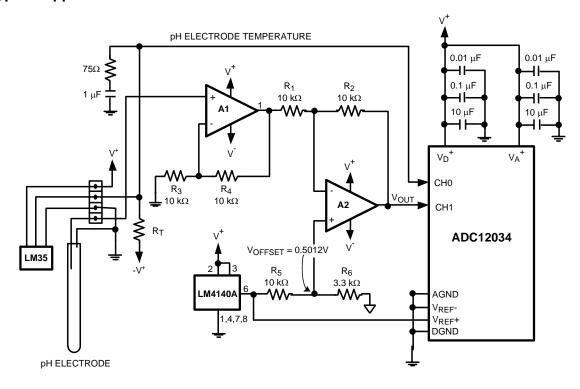


Figure 49. pH Measurement Circuit

Copyright © 2005–2015, Texas Instruments Incorporated



## **Typical Application (continued)**

#### 9.2.1 Design Requirements

pH electrodes are very high impedance sensors. As their name indicates, they are used to measure the pH of a solution. They usually do this by generating an output voltage which is proportional to the pH of the solution. pH electrodes are calibrated so that they have zero output for a neutral solution, pH = 7, and positive and negative voltages for acidic or alkaline solutions. This means that the output of a pH electrode is bipolar and must be level shifted to be used in a single supply system. The rate of change of this voltage is usually shown in mV/pH and is different for different pH sensors. Temperature is also an important factor in a pH electrode reading. The output voltage of the senor will change with temperature.

#### 9.2.2 Detailed Design Procedure

Many sensors have high source impedances that may range up to 10 M $\Omega$ . The output signal of sensors often needs to be amplified or otherwise conditioned by means of an amplifier. The input bias current of this amplifier can load the sensor's output and cause a voltage drop across the source resistance as shown in Figure 50, where  $V_{IN}^+ = V_S - I_{BIAS}^*R_S$ 

The last term,  $I_{BIAS}*R_S$ , shows the voltage drop across  $R_S$ . To prevent errors introduced to the system due to this voltage, an op amp with very low input bias current must be used with high impedance sensors. This is to keep the error contribution by  $I_{BIAS}*R_S$  less than the input voltage noise of the amplifier, so that it will not become the dominant noise factor.

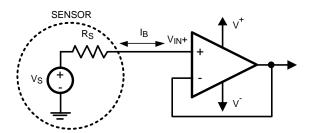


Figure 50. Noise Due to IBIAS

Figure 51 shows a typical output voltage spectrum of a pH electrode. The exact values of output voltage will be different for different sensors. In this example, the pH electrode has an output voltage of 59.15 mV/pH at 25°C.

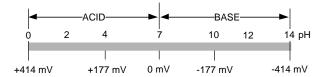


Figure 51. Output Voltage of a pH Electrode

The temperature dependence of a typical pH electrode is shown in Figure 52. As is evident, the output voltage changes with changes in temperature.

The schematic shown in Figure 49 is a typical circuit which can be used for pH measurement. The LM35 is a precision integrated circuit temperature sensor. This sensor is differentiated from similar products because it has an output voltage linearly proportional to Celcius measurement, without converting the temperature to Kelvin. The LM35 is used to measure the temperature of the solution and feeds this reading to the Analog to Digital Converter, ADC. This information is used by the ADC to calculate the temperature effects on the pH readings. The LM35 needs to have a resistor,  $R_T$  in Figure 49, to  $-V^+$  to be able to read temperatures less than  $0^{\circ}$ C.  $R_T$  is not needed if temperatures are not expected to be less than zero.

8 Submit Documentation Feedback



## **Typical Application (continued)**

The output of pH electrodes is usually large enough that it does not require much amplification; however, due to the very high impedance, the output of a pH electrode needs to be buffered before it can go to an ADC. Because most ADCs are operated on single supply, the output of the pH electrode also needs to be level shifted. Amplifier A1 buffers the output of the pH electrode with a moderate gain of +2, while A2 provides the level shifting.  $V_{OUT}$  at the output of A2 is given by:  $V_{OUT} = -2V_{DH} + 1.024V$ .

The LM4140A is a precision, low noise, voltage reference used to provide the level shift needed. The ADC used in this application is the ADC12032 which is a 12-bit, 2 channel converter with multiplexers on the inputs and a serial output. The 12-bit ADC enables users to measure pH with an accuracy of 0.003 of a pH unit. Adequate power supply bypassing and grounding is extremely important for ADCs. Recommended bypass capacitors are shown in Figure 49. It is common to share power supplies between different components in a circuit. To minimize the effects of power supply ripples caused by other components, the op amps must have bypass capacitors on the supply pins. Using the same value capacitors as those used with the ADC are ideal. The combination of these three values of capacitors ensures that AC noise present on the power supply line is grounded and does not interfere with the amplifiers' signal.

#### 9.2.3 Application Curves

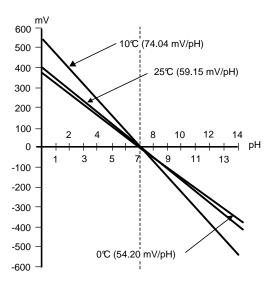


Figure 52. Temperature Dependence of a pH Electrode

Copyright © 2005–2015, Texas Instruments Incorporated



## 10 Power Supply Recommendations

For proper operation, the power supplies must be decoupled. For supply decoupling, TI recommends placing 10-nF to 1- $\mu$ F capacitors as close as possible to the operational-amplifier power supply pins. For single supply configurations, place a capacitor between the V<sup>+</sup> and V<sup>-</sup> supply pins. For dual supply configurations, place one capacitor between V<sup>+</sup> and ground, and place a second capacitor between V<sup>-</sup> and ground. Bypass capacitors must have a low ESR of less than 0.1  $\Omega$ .

Submit Documentation Feedback



## 11 Layout

## 11.1 Layout Guidelines

Take care to minimize the loop area formed by the bypass capacitor connection between supply pins and ground. A ground plane underneath the device is recommended; any bypass components to ground should have a nearby via to the ground plane. The optimum bypass capacitor placement is closest to the corresponding supply pin. Use of thicker traces from the bypass capacitors to the corresponding supply pins will lower the power supply inductance and provide a more stable power supply.

The feedback components should be placed as close to the device as possible to minimize stray parasitics.

## 11.2 Layout Example

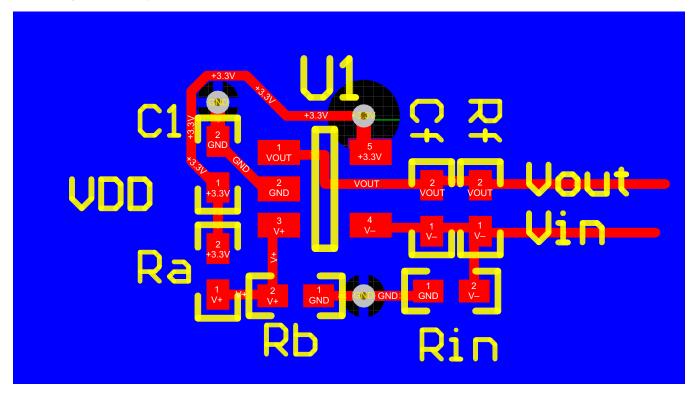


Figure 53. LMP7701 Example Layout



## 12 Device and Documentation Support

#### 12.1 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

Table 1. Related Links

PARTS	PRODUCT FOLDER	PRODUCT FOLDER SAMPLE AND BUY		TOOLS AND SOFTWARE	SUPPORT AND COMMUNITY
LMP7701	Click here	Click here	Click here	Click here	Click here
LMP7702	Click here	Click here	Click here	Click here	Click here
LMP7704	Click here	Click here	Click here	Click here	Click here

## 12.2 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E™ Online Community TI's Engineer-to-Engineer (E2E) Community. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

#### 12.3 Trademarks

LMP, E2E are trademarks of Texas Instruments.

All other trademarks are the property of their respective owners.

## 12.4 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

#### 12.5 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

## 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

www.ti.com 2-May-2025

#### **PACKAGING INFORMATION**

Orderable part number	Status (1)	Material type	Package   Pins	Package qty   Carrier	<b>RoHS</b> (3)	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
LMP7701MA/NOPB	Active	Production	SOIC (D)   8	95   TUBE	Yes	SN	Level-1-260C-UNLIM	-	LMP77 01MA
LMP7701MAX/NOPB	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-	LMP77 01MA
LMP7701MF/NOPB	Active	Production	SOT-23 (DBV)   5	1000   SMALL T&R	Yes	NIPDAU   SN	Level-1-260C-UNLIM	-40 to 125	AC2A
LMP7701MFX/NOPB	Active	Production	SOT-23 (DBV)   5	3000   LARGE T&R	Yes	NIPDAU   SN	Level-1-260C-UNLIM	-40 to 125	AC2A
LMP7702MA/NOPB	Active	Production	SOIC (D)   8	95   TUBE	Yes	SN	Level-1-260C-UNLIM	-	LMP77 02MA
LMP7702MAX/NOPB	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-	LMP77 02MA
LMP7702MM/NOPB	Active	Production	VSSOP (DGK)   8	1000   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	AA3A
LMP7702MMX/NOPB	Active	Production	VSSOP (DGK)   8	3500   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	AA3A
LMP7704MA/NOPB	Active	Production	SOIC (D)   14	55   TUBE	Yes	SN	Level-1-260C-UNLIM	-	LMP7704 MA
LMP7704MAX/NOPB	Active	Production	SOIC (D)   14	2500   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-	LMP7704 MA
LMP7704MT/NOPB	Active	Production	TSSOP (PW)   14	94   TUBE	Yes	SN	Level-1-260C-UNLIM	-40 to 125	LMP77 04MT
LMP7704MTX/NOPB	Active	Production	TSSOP (PW)   14	2500   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	LMP77 04MT

<sup>(1)</sup> **Status:** For more details on status, see our product life cycle.

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

# **PACKAGE OPTION ADDENDUM**

www.ti.com 2-May-2025

(5) MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

#### OTHER QUALIFIED VERSIONS OF LMP7704:

Space : LMP7704-SP

NOTE: Qualified Version Definitions:

Space - Radiation tolerant, ceramic packaging and qualified for use in Space-based application



www.ti.com 1-Feb-2025

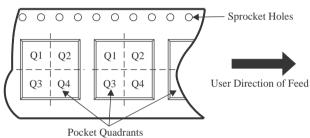
## TAPE AND REEL INFORMATION



# TAPE DIMENSIONS + K0 - P1 - B0 W Cavity - A0 -

A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

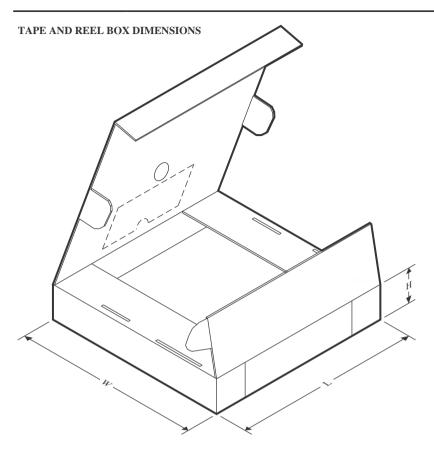


#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMP7701MAX/NOPB	SOIC	D	8	2500	330.0	12.4	6.5	5.4	2.0	8.0	12.0	Q1
LMP7701MF/NOPB	SOT-23	DBV	5	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMP7701MF/NOPB	SOT-23	DBV	5	1000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMP7701MFX/NOPB	SOT-23	DBV	5	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMP7701MFX/NOPB	SOT-23	DBV	5	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMP7702MAX/NOPB	SOIC	D	8	2500	330.0	12.4	6.5	5.4	2.0	8.0	12.0	Q1
LMP7702MM/NOPB	VSSOP	DGK	8	1000	178.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
LMP7702MMX/NOPB	VSSOP	DGK	8	3500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
LMP7704MAX/NOPB	SOIC	D	14	2500	330.0	16.4	6.5	9.35	2.3	8.0	16.0	Q1
LMP7704MTX/NOPB	TSSOP	PW	14	2500	330.0	12.4	6.95	5.6	1.6	8.0	12.0	Q1



www.ti.com 1-Feb-2025



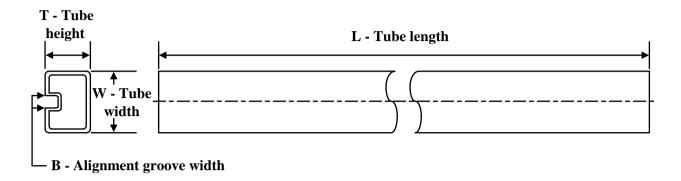
\*All dimensions are nominal

7 til dilliciololio die Hollina							
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMP7701MAX/NOPB	SOIC	D	8	2500	356.0	356.0	35.0
LMP7701MF/NOPB	SOT-23	DBV	5	1000	208.0	191.0	35.0
LMP7701MF/NOPB	SOT-23	DBV	5	1000	210.0	185.0	35.0
LMP7701MFX/NOPB	SOT-23	DBV	5	3000	210.0	185.0	35.0
LMP7701MFX/NOPB	SOT-23	DBV	5	3000	208.0	191.0	35.0
LMP7702MAX/NOPB	SOIC	D	8	2500	356.0	356.0	35.0
LMP7702MM/NOPB	VSSOP	DGK	8	1000	208.0	191.0	35.0
LMP7702MMX/NOPB	VSSOP	DGK	8	3500	356.0	356.0	35.0
LMP7704MAX/NOPB	SOIC	D	14	2500	356.0	356.0	35.0
LMP7704MTX/NOPB	TSSOP	PW	14	2500	356.0	356.0	35.0

# **PACKAGE MATERIALS INFORMATION**

www.ti.com 1-Feb-2025

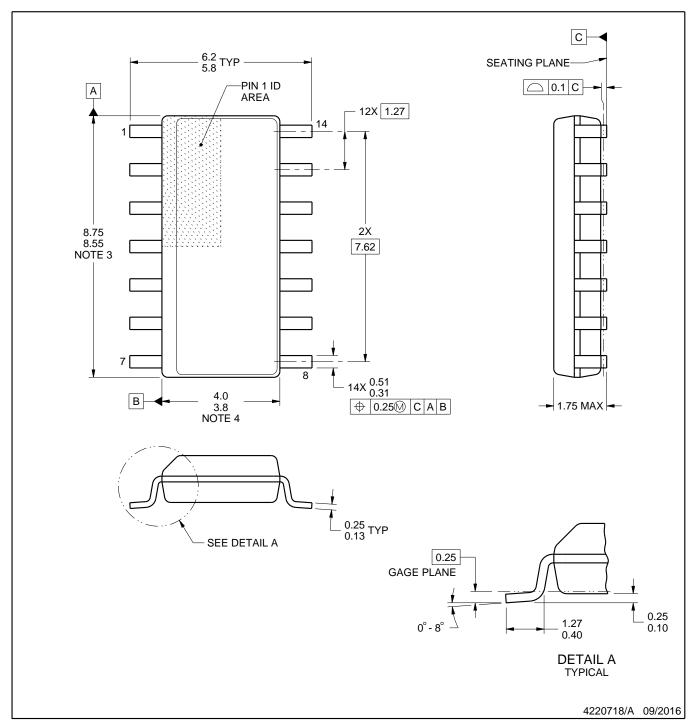
### **TUBE**



\*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
LMP7701MA/NOPB	D	SOIC	8	95	495	8	4064	3.05
LMP7702MA/NOPB	D	SOIC	8	95	495	8	4064	3.05
LMP7704MA/NOPB	D	SOIC	14	55	495	8	4064	3.05
LMP7704MT/NOPB	PW	TSSOP	14	94	495	8	2514.6	4.06



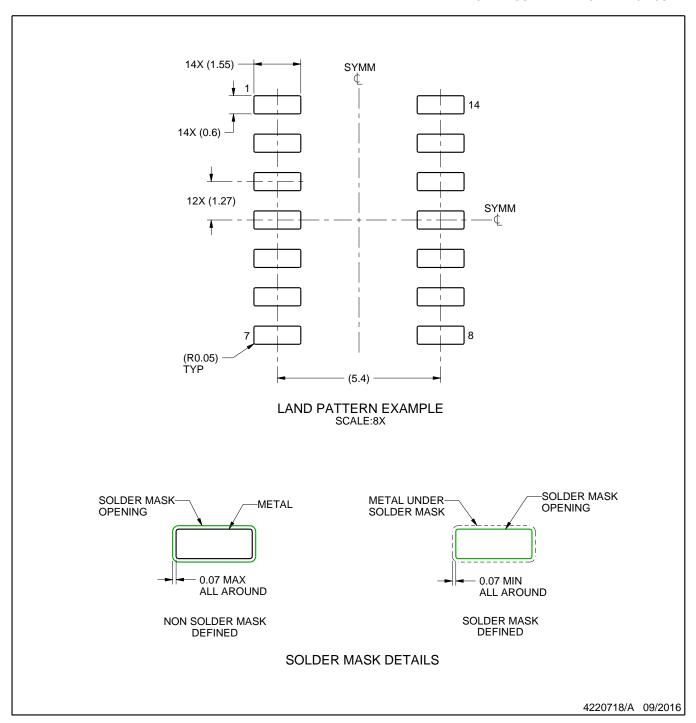


- 1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm, per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.43 mm, per side.
- 5. Reference JEDEC registration MS-012, variation AB.

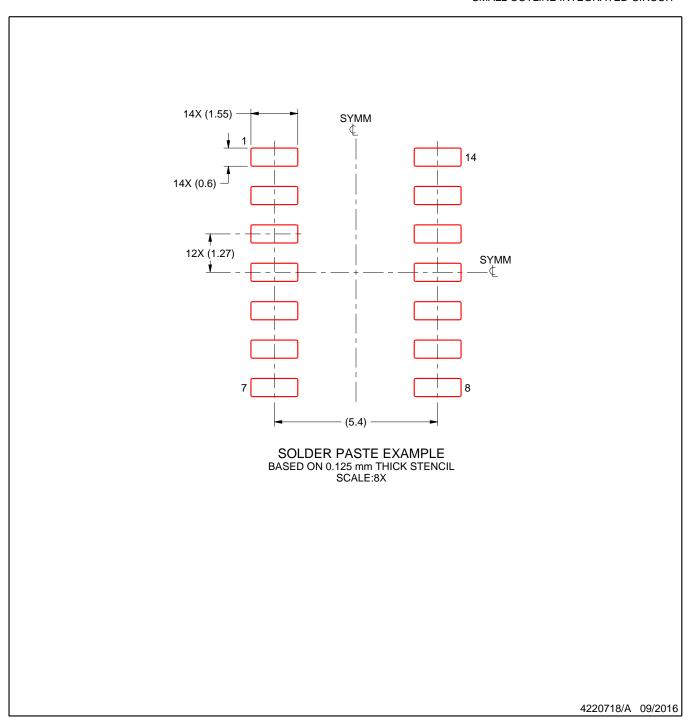




NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

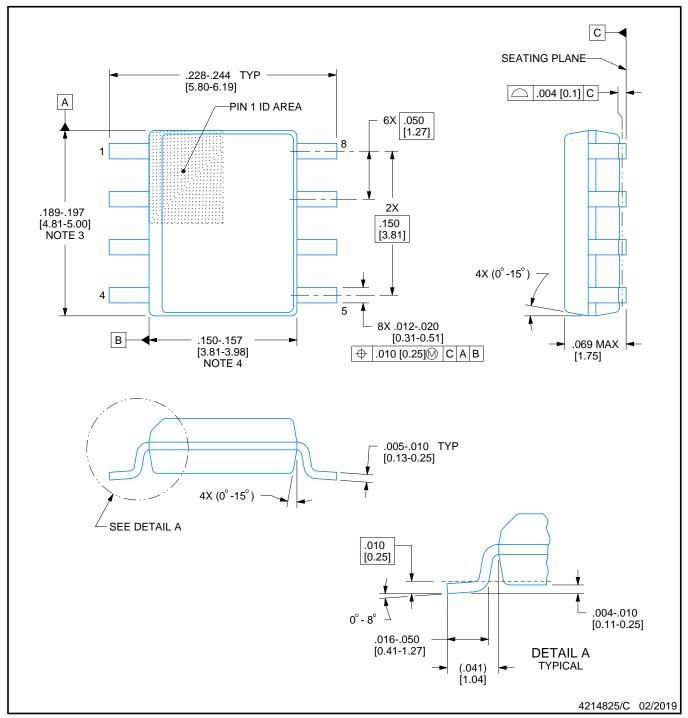




- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.







- 1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.





NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

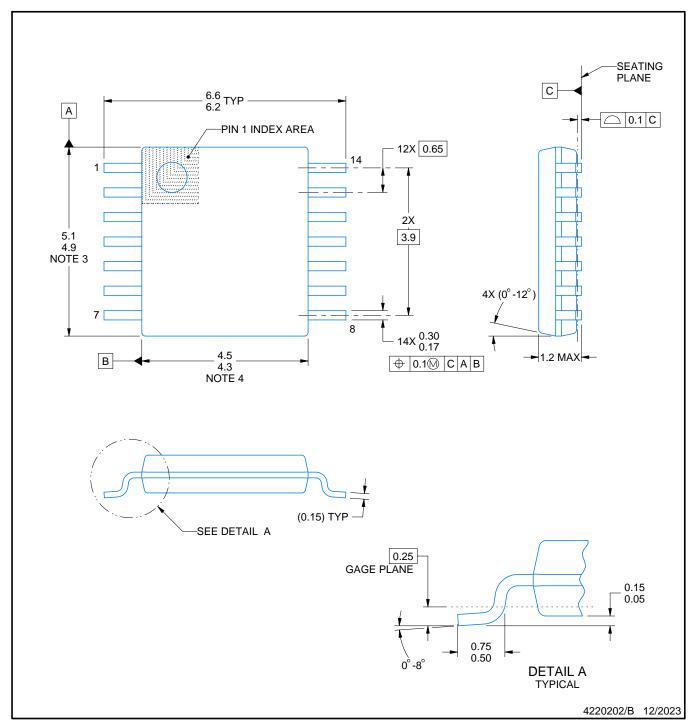




- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.





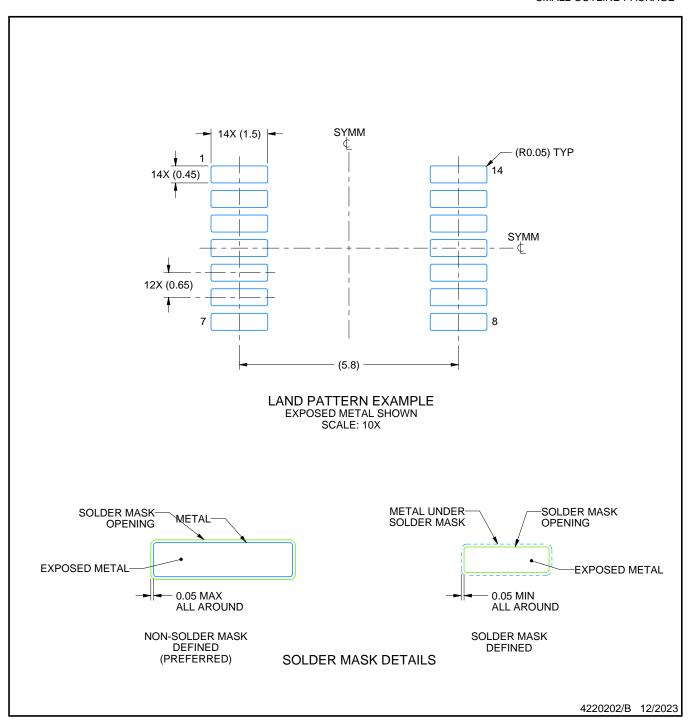


- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-153.

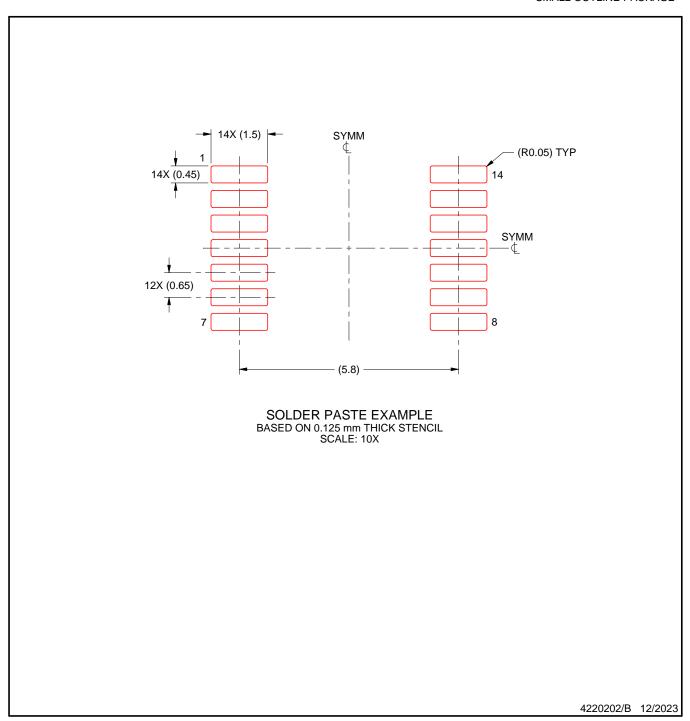




NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.



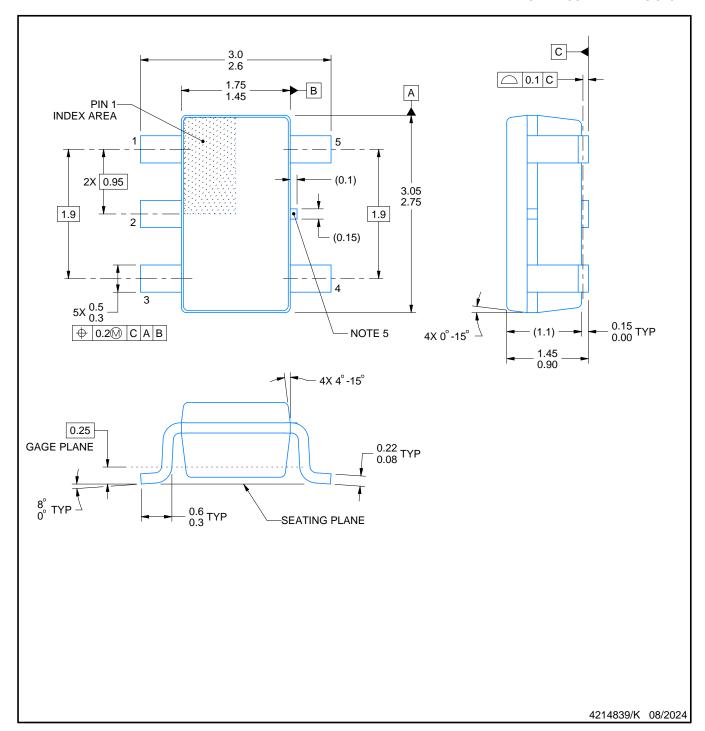


- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.





SMALL OUTLINE TRANSISTOR

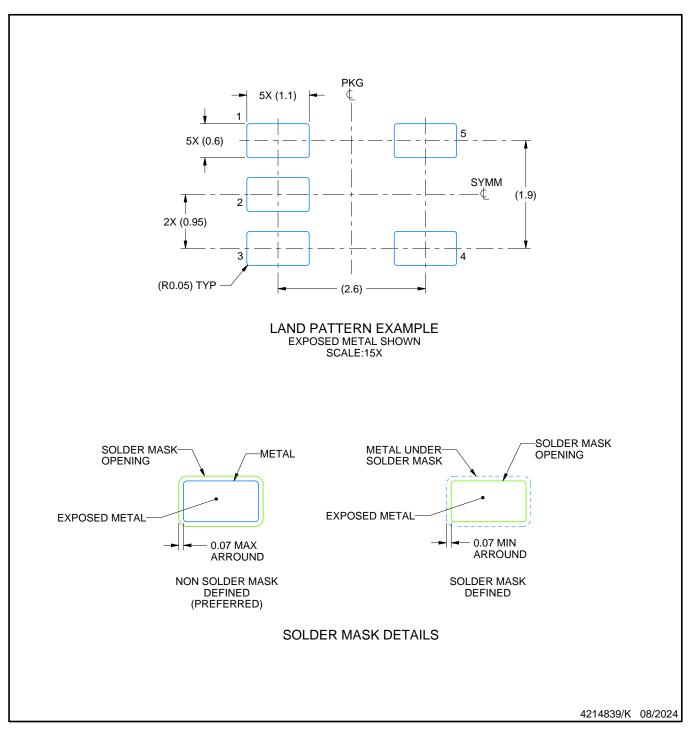


- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
  2. This drawing is subject to change without notice.
  3. Reference JEDEC MO-178.

- 4. Body dimensions do not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.25 mm per side.
- 5. Support pin may differ or may not be present.



SMALL OUTLINE TRANSISTOR

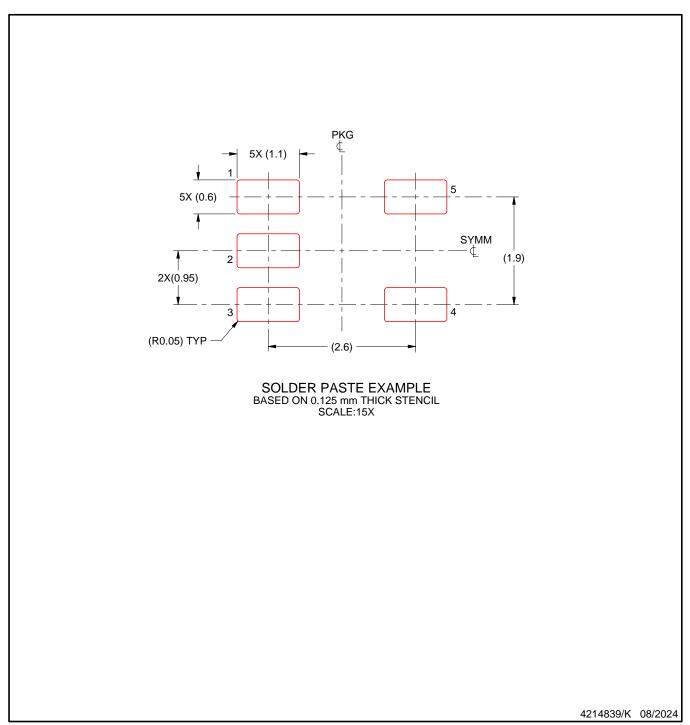


NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.



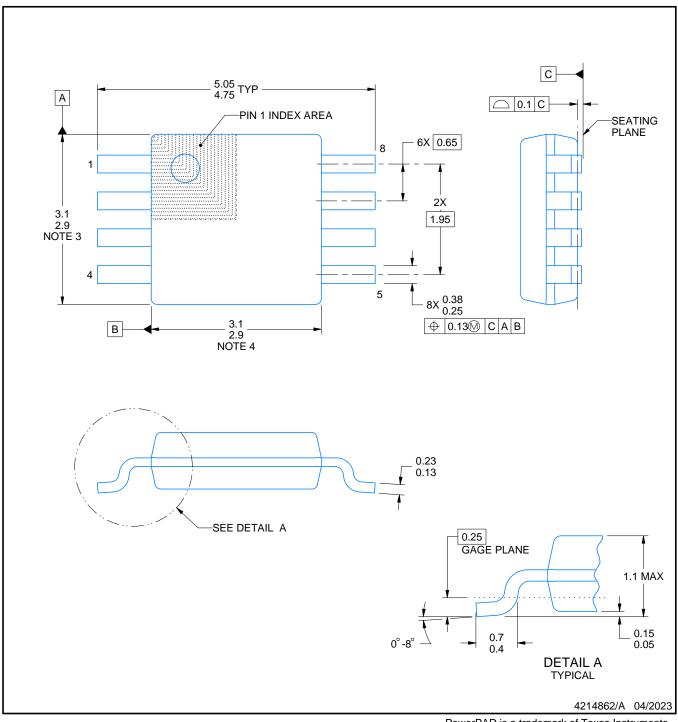
SMALL OUTLINE TRANSISTOR



- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.







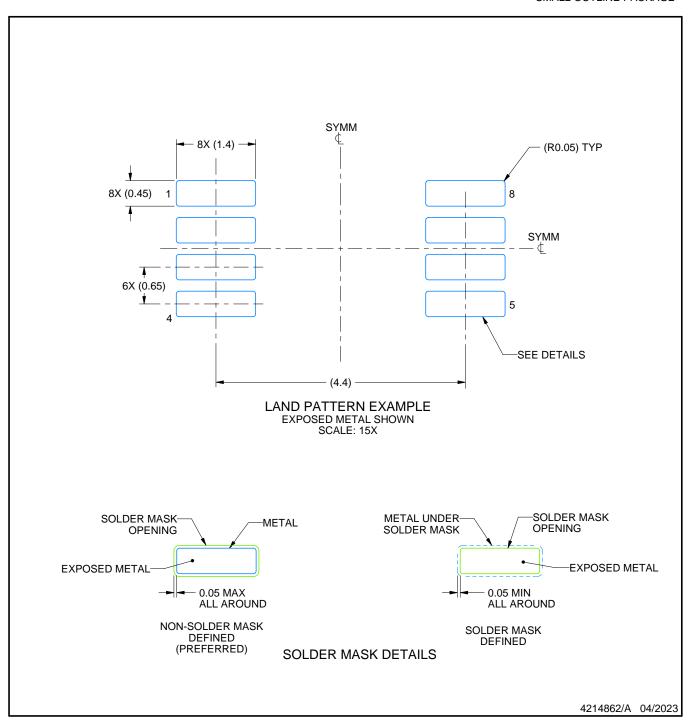
PowerPAD is a trademark of Texas Instruments.

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

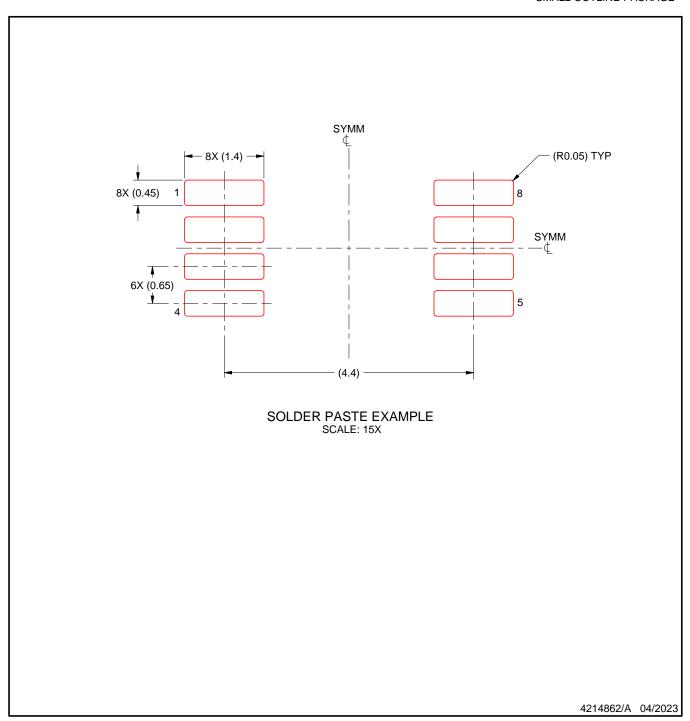
  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-187.





- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
- 8. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.
- 9. Size of metal pad may vary due to creepage requirement.





- 11. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 12. Board assembly site may have different recommendations for stencil design.



#### IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2025. Texas Instruments Incorporated